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# On Solutions of a Stochastic Integral Equation of the Volterra-Fredholm Type 

O rozwiqzaniach stochastycznego równania całkowego typu Voltery-Fredholma

$$
\begin{aligned}
& \text { Abstract. The aim of this paper is the study of the mixed random Volterra-Frdhulm equation } \\
& \text { of the form } \\
& \qquad \begin{aligned}
x(t ; \omega) & =h(t, x(t, \omega))+\int_{0}^{t} k_{1}(t, \tau ; \omega) f_{1}(\tau, x(\tau ; \omega)) d \tau \\
& +\int_{0}^{\infty} k_{2}(t, \tau ; \omega) f_{2}(\tau, x(\tau ; \omega)) d \tau
\end{aligned}
\end{aligned}
$$

under less restrictive conditions than those of [9] and [10]. Namely, we only assume that $f_{1}$ and $f_{2}$ are sublinear functions.

1. Introduction. The aim of this paper is to investigate the existence and the stability of stochastic integral equation of Volterra-Fredholm type. Problems concerning stochastic differential and integral equations have been treated in many papers and monographs (cf. [3], [4], [7], [8], [9], [10], [11], [12], [13]). The aim of this paper is to give a new existence theorem for a stochastic integral equation of the Volterra-Fredholm type of [9] and [10] (cf. also [13]) and to investigate the asymptotic behaviour and the stability of solutions of that equation.

The most important problem examined up to now is that one concerning the existence of solutions of considered equations. It is solved mostly by the Banach fixed point principle, the Schauder fixed point theorem and successive approximations (cf. [3], [4], [7], [9], [10], [11], [12], [13]). This paper uses the notion of measure of noncompactness in a Banach space and the fixed-point theorem of Darbo type, cf. [2], [6]. This approach allows us to weaken conditions of (cf. [9], [10], [13]). Namely, we replace the Lipschitz type conditions by those with sublinear functions. The asymptotic stability in mean square is also investigated here.

We shall deal with a stochastic integral equation of the Volterra Fredholm type of the form

$$
\begin{align*}
x(t ; \omega) & =h(t, x(t ; \omega))+\int_{0}^{t} k_{1}(t, \tau ; \omega) f_{1}(\tau, x(\tau ; \omega)) d \tau  \tag{1.1}\\
& +\int_{0}^{\infty} k_{2}(t, \tau ; \omega) f_{2}(\tau, r(\tau ; \omega)) d r
\end{align*}
$$

where $t \geq 0$ and
(i) $\omega \in \Omega$, where $\Omega$ is the supporting set of the complete probability measure space $(\Omega, \mathcal{A}, P)$;
(ii) $x(t ; \omega)$ is the unknown random function for $t \in \mathbf{R}_{+}$(= the set of nomegative real numbers);
(iii) $h$ is a scalar function $h: \mathbf{R}_{+} \times \mathbf{R} \rightarrow \mathbf{R}$;
(iv) $f_{1}(t, x)$ is a scalar function of $t \in \mathbf{R}_{+}$and $x \in \mathbf{R}$;
(v) $f_{2}(t, x)$ is a scalar function defined for $t \in \mathbf{R}_{+}$and $x \in \mathbf{R}$, the real line;
(vi) $k_{1}(t, \tau ; \omega)$ is a stochastic kernel defined for $t$ and $\tau$ satisfying $0 \leq \tau \leq t<\infty$;
(vii) $k_{2}(t, \tau ; \omega)$ is a stochastic kernel defined for $t$ and $\tau$ in $\mathbf{R}_{+}$.
2. Mathematical preliminaries. We shall give here some mathematical concepts that are essential in understanding the details of this paper.

We now give the following definitions.
Definition 2.1. We shall call $x(t ; \omega)$ a random solution of the stochastic integral equation (1.1) if for every fixed $t \in \mathbf{R}_{+}, x(t ; \omega) \in L^{2}(\Omega, \mathcal{A}, P)$ and satisfies (1.1) P-a.e.

Deflinition 2.2. A random solution $x(t ; \omega)$ is said to be asymptotically stable in mean square if

$$
\lim _{t \rightarrow \infty} E|x(t ; \omega)|^{2}=0
$$

Throughout this paper $\mathcal{X}$ will denote an infinitely dimensional real Banach space with norm \|| \| and the zero element $0 . V(x, r)$ stands for the closed ball centered at $x$ of radius $r$. Denote by $\mathcal{M}_{x}$ the family of all nonempty bounded subsets of $\mathcal{X}$, and by $\mathcal{N}_{\mathcal{X}}$ the family of all relatively compact and nonempty subsets of $\mathcal{X}$.

The following axioms defining a measure of noncompactness are taken from Banaś and Goebel [2].

Deflnition 2.3. A nonempty family $\mathcal{B} \subset \mathcal{N}_{\mathcal{X}}$ is said to be the kernel (of measure of compactness), provided it satisfies the following conditions:
$1^{\circ} U \in \mathcal{B} \Longrightarrow \bar{U} \in \mathcal{B}$;
$2^{\circ} U \in \mathcal{B}, V \subset U, V \neq \emptyset \Longrightarrow V \in \mathcal{B} ;$
$3^{\circ} U, V \in \mathcal{B} \Longrightarrow \lambda U+(1-\lambda) V \in \mathcal{B}, \lambda \in[0,1]$;
$4^{\circ} U \in \mathcal{B} \Longrightarrow$ Conv $U \in \mathcal{B}$;
$5^{\circ} \mathcal{B}^{c}$ (the subfamily of $\mathcal{B}$ consisting of all closed sets) is closed in $\mathcal{N}^{c}$ with respect to the topology generated by Hausdorff metric.

Definition 2.4. The function $\mu: \mathcal{M}_{X} \rightarrow[0,+\infty)$ is said to be a measure of noncompactness with the kernel $(\operatorname{ker} \mu=\mathcal{B})$ if it satisfies the following conditions :

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\(1^{\circ} \mu(U)=0 \Longleftrightarrow U \in \mathcal{B} ;\)
\(2^{\circ} \mu(U)=\mu(\bar{U}) ;\)
\(3^{\text {b }} \mu(\operatorname{Conv} U)=\mu(U)\);
\(4^{\circ} U \subset V \Longrightarrow \mu(U) \leq \mu(V)\);
\(5^{\circ} \mu(\lambda U+(1-\lambda) V) \leq \lambda \mu(U)+(1-\lambda) \mu(V), \lambda \in[0,1] ;\)
\(6^{\circ}\) if \(U_{n} \in \mathcal{M}_{r}, U_{n}=\bar{U}_{n}\), and \(U_{n+1} \subset U_{n}, n=1,2, \ldots\), and if \(\lim _{n \rightarrow \infty} \mu\left(U_{n}\right)=0\),
``` then \(U=\bigcap_{n=1}^{\infty} U_{n} \neq \emptyset\).

If a measure of noncompactness \(\mu\) satisfies in addition the following two conditions:
\[
\begin{aligned}
& 7^{\circ} \mu(U+V) \leq \mu(U)+\mu(V) \\
& 8^{\circ} \mu(\lambda U)=|\lambda| \mu(U), \lambda \in \mathbf{R}
\end{aligned}
\]
it will be sublinear.

Let \(M \subset \mathcal{X}\) be a nonempty set and let \(\mu\) be a measure of noncompactness on \(\mathcal{X}\).

Deflnition 2.5. We say that a continuous mapping \(T: M \rightarrow \mathcal{X}\) is a contraction with respect to \(\mu\) ( \(\mu\)-contraction) if for any set \(U \in \mathcal{M}_{x}\) its image \(T U \in \mathcal{M}_{x}\), and there exists a constant \(k \in[0,1)\) such that
\[
\mu(T U) \leq k \cdot \mu(U)
\]

We shall use the following modified version of the fixed-point theorem of Darbo type.

Theorem 2.1. Let \(C\) be a nonempty, closed, convex and bounded sct of \(\mathcal{X}\) and let \(T: C \rightarrow C\) be an arbitrary \(\mu\)-contraction. Then \(T\) has at least one fixed point in \(C\) and the set Fix \(T=\{x \in C: T x=x\}\) of all fixed points of \(T\) belongs to ker \(\mu\).

Let \(C_{p}\left(\mathbf{R}_{+}, L^{2}(\Omega, \mathcal{A}, P), p\right)\) (or shortly \(\left.C_{p}\right)\) denote a space of all continuous maps \(x(t ; \cdot)\) from \(\mathbf{R}_{+}\)into \(L^{2}(\Omega, \mathcal{A}, P)\) with the topology defined by the norm
\[
\|x\|_{P}=\sup \left\{p(t)\|x(t)\|_{L^{2}}: t \geq 0\right\}<\infty .
\]

The space \(C_{p}\) with norm \(\left\|\|_{p}\right.\) is a real Banach space (see Banaś [1], Zima [14]).
Now for \(x \in C_{p}, U \in \mathcal{M}_{C}, T>0\), and \(\varepsilon>0\), we put
\[
\beta^{T}(x, \varepsilon)=\sup \left\{\|p(t) x(t)-p(s) x(s)\|_{L^{2}}: t, s \in[0, T],|t-s| \leq \varepsilon\right\} ;
\]
\[
\begin{aligned}
& \beta_{0}^{T}(U, \varepsilon)=\sup \left\{\beta^{T}(x, \varepsilon): x \in U\right\} \\
& \beta_{0}^{T}(U)=\lim _{e \rightarrow 0} \beta^{T}(U, \varepsilon) ; \\
& \beta_{0}\left(U^{I}\right)=\lim _{V_{\rightarrow \infty}} \beta_{0}^{T}(U) ; \\
& a\left(U^{I}\right)=\lim _{T \rightarrow \infty} \sup _{x \in U} \sup _{i \geq T}\|x(t)\|_{L^{2}} p(t) ; \\
& b\left(U^{\prime}\right)=\lim _{T \rightarrow \infty} \sup _{s, t \geq T}\left\{\|p(t) x(t)-p(s) x(s)\|_{L^{2}}\right\} ; \\
& \mu_{0}(U)=\beta_{0}(U)+a(U)+\sup \{p(t) m(U(t)): t \geq 0\} ; \\
& \mu_{1}(U)=\beta_{0}(U)+b(U)+\sup \{p(t) m(U(t)): t \geq 0\},
\end{aligned}
\]
where \(m\) is a sublinear measure of noncompactness on \(\mathcal{M}_{L^{2}(\Omega, A, P)}\) and
\[
U(t)=\left\{x(t) \in L^{2}(\Omega, \mathcal{A}, P): x \in U\right\}
\]

The functions \(\mu_{0}\) and \(\mu_{1}\) define sublinear measure of noncompactness on \(\mathcal{M}_{\boldsymbol{p}}\) (see [1], [2]). It is also known (see [1], [2]) that ker \(\mu_{0}\) is the set of all sets \(\left[{ }^{l} \in \mathcal{M}_{c_{p}}\right.\) such that the functions belonging to \(U\) are equicontinuous on any compact of \(\mathbf{R}_{+}\)and
\[
\lim _{i \rightarrow \infty} p(t)\|x(t)\|_{L^{2}}=0
\]
uniformly with respect to \(x \in U\). Further properties of \(\mu_{0}\) and \(\mu_{1}\) can be found in [1] and [2].
3. Main results. We make the following assumptions concerning the equation (1.1).

For each \(t\) and \(\tau\) such that \(0 \leq \tau \leq t<\infty\) the stochastic kernel \(k_{1}(t, \tau ; \omega)\) has values in \(L_{\infty}(\Omega, \mathcal{A}, P)\) and the stochastic kernel \(k_{2}(t, \tau ; \omega)\) for each \(t\) and \(\tau\) in \(\mathbf{R}_{+}\)has values in \(L_{\infty}(\Omega, \mathcal{A}, P)\).

The mappings
\[
(t, \tau) \rightarrow k_{1}(t, \tau ; \omega) \text { and }(t, \tau) \rightarrow k_{2}(t, \tau ; \omega)
\]
from the sets
\[
\Delta_{1}=\{(t, \tau): 0 \leq \tau \leq t<\infty\} \text { and } \Delta_{2}=\{(t, \tau): 0 \leq \tau<\infty, 0 \leq t<\infty\}
\]
respectively, into \(L_{\infty}(\Omega, \mathcal{A}, P)\) are continuous.
We define for \(0 \leq \tau<t<\infty\),
\[
k_{1}(t, \tau)=P-\underset{\omega \in \Omega}{-\operatorname{ess} \sup }\left|k_{1}(t, \tau ; \omega)\right|,
\]
and for each \(t\), and \(\tau\) in \(\mathbf{R}_{+}\)
\[
k_{2}(t, \tau)=P-\underset{\omega \in \Omega}{-\operatorname{ess} \sup }\left|k_{2}(t, \tau ; \omega)\right|
\]

The above assumptions imply that if \(x \in C_{p}\) then for rach \(t \in \mathbf{R}_{+}\)
\[
\left\|k_{i}(t, \tau): r(\tau)\right\|_{L_{c^{2}}} \leq k_{i}(t, \tau)\|x(\tau)\|_{L^{2}}, \quad i=1,2
\]

Theorem 3.1. Suppose that the functions \(f_{i}, i=1,2\), and \(h\) in the stochastic. integral equation of the Volterra-Fredholm type (1.1) satisfy the following conditions :
(i) functions \(f_{i}: \mathbf{R}_{+} \times \mathbf{R} \rightarrow \mathbf{R}, i=1,2\), are sublinear, that are \(\left|f_{i}(t, x(t ; \omega))\right| \leq\) \(u_{i}(t)|x(t ; \omega)|+v_{i}(t) P\)-a.s., \(i=1,2\), for some nonnegative functions \(u_{i}\) and \(v_{i}, i=1,2\), are continuous and defined for \(t \in \mathbf{R}_{+}\), and let us denote
\[
\begin{aligned}
A= & \sup \left\{p ( t ) \left(\int_{0}^{t} k_{1}(t, \tau)\left(u_{1}(\tau) / p(\tau)\right) d \tau\right.\right. \\
& \left.\left.+\int_{0}^{\infty} k_{2}(t, \tau)\left(u_{2}(\tau) / p(\tau)\right) d \tau\right): t \in \mathbf{R}_{+}\right\} \\
B(t)= & p(t)\left(|h(t, 0)|+\int_{0}^{t} k_{1}(t, \tau) v_{1}(\tau) d \tau\right. \\
& \left.+\int_{0}^{\infty} k_{2}(t, \tau) v_{2}(\tau) d \tau\right) \quad \text { for } t \in \mathbf{R}_{+} \\
B= & \sup \left\{B(t): t \in \mathbf{R}_{+}\right\}<\infty
\end{aligned}
\]

Suppose that
(ii) \(\lim _{t \rightarrow \infty} B(t)=0\);
(iii) \(\mid h t, x(t ; \omega))-h(t, y(t ; \omega))|\leq k| x(t ; \omega)-y(t ; \omega) \mid P_{-a . s .}\) for \(k \in[0,1)\);
(iv) \(M:=k+A<1\);
(v) for any given but fixed \(T>0\)
\[
\lim _{\varepsilon \rightarrow 0} \sup \left\{\|h(t, x(s))-h(s, x(s))\|_{L^{2}}: s, t \in[0, T],|t-s| \leq \varepsilon\right\}=0
\]
uniformly with respect to \(x \in U \subset V(0, r)\), where \(r=B /(1-M)\);
(vi) the mappings \(x(t ; \omega) \rightarrow f_{i}(t, x(t ; \omega)), i=1,2, C_{p}\left(\mathbf{R}_{+}, L^{2}(\Omega, \mathcal{A} P), p\right)\) into \(C_{p}\left(\mathbf{R}_{+} \cdot L^{2}(\Omega, \mathcal{A}, P), p\right)\) are continuous in the topology generated by the norm \(\|\cdot\|_{p i}\);
(vii) \(\lim _{t \rightarrow \infty} p(t)\left\|f_{i}(t, x(t))-f_{i}(t, y(t))\right\|_{L^{2}}=0, i=1,2\), uniformly with respect to \(x\) and \(y\) belonging to \(V(0, r), r=B /(1-M)\);
(viii) there exist \(L_{i}, i=1,2,3\), satisfying \(0 \leq L_{1}+L_{2}+L_{3}<1\) such that
\[
\begin{aligned}
& m\left(\int_{0}^{t} k_{1}(t, \tau ; \omega) f_{1}(\tau, U(\tau)) d \tau\right) \leq L_{1} m(U(t)) \\
& m\left(\int_{0}^{\infty} k_{2}(t, \tau ; \omega) f_{2}(\tau, U(\tau)) d \tau\right) \leq L_{2} m(U(t)) \\
& m(h(t, U(t))) \leq L_{3} m(U(t)), L_{i} \in[0,1), i=1,2,3 \\
& U(t)=\left\{x(s) \in L^{2}(\Omega, \mathcal{A} P), s \geq 0, x \in U \subset V(0, r):\right.
\end{aligned}
\]
\[
\left.p(t)\|x(t)\|_{L^{2}} \leq\|U\|_{p}\right\}, t \geq 0, \text { where } r=B /(1-M) .
\]

Then there exists at least one solution \(x \in C_{p}\) of equation (1.1) such that
\[
\lim _{i \rightarrow \infty} p(t)\|x(t)\|_{L^{2}}=0
\]

Proof. Define the \(H\) on \(C_{p}\) by
\[
\begin{aligned}
(H x)(t ; \omega) & =h(t, x(t ; \omega))+\int_{0}^{t} k_{1}(t, \tau ; \omega) f_{1}(\tau, x(\tau ; \omega)) d \tau \\
& +\int_{0}^{\infty} k_{2}(t, \tau ; \omega) f_{2}(\tau, x(\tau ; \omega)) d \tau
\end{aligned}
\]

Using assumption (i), (ii) and (3.1) we get for \(x \in C_{p}\)
\[
\begin{aligned}
& p(t)\|(H x)(t)\|_{L^{2}} \leq p(t)\left(k\|x(t)\|_{L^{2}}+|h(t, 0)|\right. \\
& \left.+\int_{0}^{t} k_{2}(t, \tau)\left\|f_{1}(\tau, x(\tau))\right\|_{L^{2}} d \tau+\int_{0}^{\infty} k_{2}(t, \tau)\left\|f_{2}(\tau, x(\tau))\right\|_{L^{2}} d \tau\right) \\
& \leq\|x\|_{p}\left(k+p(t)\left(\int_{0}^{t} k_{1}(t, \tau)\left(u_{1}(\tau) / p(\tau)\right) d \tau+\int_{0}^{\infty} k_{2}(t, \tau)\left(u_{2}(\tau) / p(\tau)\right) d \tau\right)\right) \\
& +p(t)\left(|h(t, 0)|+\int_{0}^{t} k_{1}(t, \tau) v_{1}(\tau) d \tau+\int_{0}^{\infty} k_{2}(t, \tau) v_{2}(\tau) d \tau\right)
\end{aligned}
\]

Hence, we get
\[
\|H x\| \leq M\|x\|_{p}+B
\]
which implies that \(H\) maps \(C_{p}\) into \(C_{p}\). Moreover, we note that
\[
H: V(0, r) \rightarrow V(0, r) \text { for } r=B /(1-M)
\]

We now prove that the map \(H\) is continuous in the ball \(V(0, r)\). Let \(x, y \in V(0, r)\). By assumption (vii) for any given \(\varepsilon_{i}>0, i=1,2\), we can choose \(T>0\) such that
\[
\begin{equation*}
p(\tau)\left\|f_{i}(\tau, x(\tau))-f_{i}(\tau, y(\tau))\right\|_{L^{2}}<\varepsilon_{i}, \quad \text { whenever } \tau>T \tag{3.3}
\end{equation*}
\]

On the other hand, by (vi), for any given \(\varepsilon^{(i)}>0, i=1,2\), there exist \(\delta_{i}>0, i=1,2\), such that for all \(\tau \in[0, T]\)
\[
\begin{align*}
& p(\tau)\left\|f_{i}(\tau, x(\tau))-f_{i}(\tau, y(\tau))\right\|_{L^{2}}<\varepsilon^{(i)}, \quad i=1,2,  \tag{3.4}\\
& \text { whenever }\|x-y\|_{p}<\delta_{i}, \quad i=1,2
\end{align*}
\]

Moreover, by (iii), for any given \(\varepsilon_{3}>0\) there exists \(\delta>0\) such that
\[
\begin{align*}
& p(t)\|h(t, x(t))-h(t, y(t))\|_{L^{2}}<\varepsilon_{3},  \tag{3.5}\\
& \text { whenever }\|x-y\|_{p}<\delta .
\end{align*}
\]

Furthermore, we can assume without loss of generality that there exists \(T>0\) such that \(u_{i}(t) \geq 1, i=1,2\), whenever \(t \geq T\), and \(u_{T}^{i}=\min \left\{u_{i}(\tau): 0 \leq \tau \leq T\right\}>0\), \(i=1,2\).

Hence, using (3.5), and putting \(p_{T}=\max \{p(\tau): 0 \leq \tau \leq T\}\) we have for \(t \geq T\)
\[
\begin{align*}
& p(t)\|(H x)(t)-(H y)(t)\|_{L^{2}} \leq p(t)\left(\|h(t, x(t))-h(t, y(t))\|_{L^{2}}\right.  \tag{3.6}\\
& +\int_{0}^{t} k_{1}(t, \tau)\left\|f_{1}(\tau, x(\tau))-f_{1}(\tau, y(\tau))\right\|_{L^{2}} d \tau \\
& +\int_{0}^{\infty} k_{2}(t, \tau)\left\|f_{2}(\tau, x(\tau))-f_{2}(\tau, y(\tau))\right\|_{L^{2}} d \tau<\varepsilon_{3} \\
& +p(t)\left(\left(p_{T} / u_{1}^{T}\right) \cdot \int_{0}^{T} k_{1}(t, \tau)\left(u_{1}(\tau) / p(\tau)\right) \| f_{1}(\tau, x(\tau))\right. \\
& -f_{1}(\tau, y(\tau)) \|_{L^{2}} d \tau+\int_{T}^{t} k_{1}(t, \tau)\left(u_{1}(\tau) / p(\tau)\right) p(\tau) \\
& \left.\cdot\left\|f_{1}(\tau, x(\tau))-f_{1}(\tau, y(\tau))\right\|_{L^{2}} d \tau\right) \\
& +p(t)\left(\left(p_{T} / u_{2}^{T}\right) \cdot \int_{0}^{T} k_{2}(t, \tau)\left(u_{2}(\tau) / p(\tau)\right) p(\tau) \| f_{2}(\tau, x(\tau))\right. \\
& -f_{2}(\tau, y(\tau)) \|_{L^{2}} d \tau+\int_{T}^{\infty} k_{2}(t, \tau)\left(u_{2}(\tau) / p(\tau)\right) p(\tau) . \\
& \left.\cdot\left\|f_{2}(\tau, y(\tau))-f_{2}(\tau, y(\tau))\right\|_{L^{2}} d \tau\right) .
\end{align*}
\]

Therefore, by (iv), (3.3), (3.4) and (3.6) we obtain
\[
\begin{align*}
& \sup _{i \geq T} p(t)\|(H x)(t)-(H y)(t)\|_{L^{2}} \leq \varepsilon_{3}+M\left(\left(p_{T} / u_{1}^{T}\right) \varepsilon^{(1)}\right.  \tag{3.7}\\
& \left.+\varepsilon_{1}+\left(p_{T} / u_{2}^{T}\right) \varepsilon^{(2)}+\varepsilon_{2}\right) .
\end{align*}
\]

Moreover, it can be seen that for any given \(\varepsilon_{4}>0\) one has
\[
\begin{aligned}
& \sup _{0 \leq i \leq T} p(t)\|(H x)(t)-(H y)(t)\|_{L^{2}}<\varepsilon_{4}, \\
& \text { whenever }\|x-y\|_{p}<\delta .
\end{aligned}
\]

Thus by (3.7) and (3.8), for any given \(\varepsilon>0\|H x-H y\|_{p}<\varepsilon\), whenever \(\|x-y\|_{p}<\delta\), \(x, y \in V(0, r)\).

Let now be given \(\varepsilon>0, T>0\) and \(t, s \in[0, T],|t-s|<\varepsilon\). By (3.2) for \(0 \leq s \leq t\)
and \(x \in U \subset V(0, r)\), we have
\[
\begin{align*}
& \|p(t)(H x)(t)-p(s)(H x)(s)\|_{L^{2}} \leq|p(t)-p(s)| \cdot  \tag{3.9}\\
& \cdot\|h(t, x(t))\|_{L^{2}}+p(s)\|h(t, x(t))-h(s, x(s))\|_{L^{2}} \\
& +|p(t)-p(s)|\left\|\int_{0}^{t} k_{1}(t, \tau) f_{1}(\tau, x(\tau)) d \tau\right\|_{L^{2}} \\
& +p(s)\left\|\int_{0}^{t}\left(k_{1}(t, \tau)-k_{1}(s, \tau)\right) f_{1}(\tau, x(\tau)) d \tau\right\|_{L^{2}} \\
& +p(s)\left\|\int_{J^{*}}^{t} k_{1}(t, \tau) f_{1}(\tau, x(\tau)) d \tau\right\|_{L^{2}}+|p(t)-p(s)| \cdot \\
& \cdot\left\|\int_{0}^{\infty} k_{2}(t, \tau) f_{2}(\tau, x(\tau)) d \tau\right\|_{L^{2}}+p(s) \\
& \cdot\left\|\int_{0}^{\infty}\left(k_{2}(t, \tau)-k_{2}(s, \tau)\right) f_{2}(\tau, x(\tau)) d \tau\right\|_{L^{2}}
\end{align*}
\]

But using (3.1) with \(i=1\) and \(x\) replaced by \(f_{1}(\tau, x(\tau))\), we obtain
\[
\begin{align*}
& |p(t)-p(s)|\left\|\int_{0}^{t} k_{1}(t, \tau) f_{1}(\tau, x(\tau)) d \tau\right\|_{L^{2}}  \tag{3.10}\\
& \leq|p(t)-p(s)| \cdot \int_{0}^{t} k_{1}(t, \tau)\left\|u_{1}(\tau)|x(\tau)|+v_{1}(\tau)\right\|_{L^{2}} d \tau \\
& \leq T|p(t)-p(s)| \cdot\left(r \cdot \max \left\{k_{1}(t, \tau)\left(u_{1}(\tau) / p(\tau)\right): 0 \leq \tau \leq T\right\}\right. \\
& \left.+\max \left\{k_{1}(t, \tau) v_{1}(\tau): 0 \leq \tau \leq T\right\}\right)
\end{align*}
\]

Similarly we get
\[
\begin{align*}
& p(s)\left\|\int_{0}^{t}\left(k_{1}(t, \tau)-k_{1}(s, \tau)\right) f_{1}(\tau, x(\tau)) d \tau\right\|_{L^{2}}  \tag{3.11}\\
& \leq \operatorname{Trp}(s) \max \left\{\mid k_{1}(t, \tau)-k_{1}\left(s, \tau \mid\left(u_{1}(\tau) / p(\tau)\right): 0 \leq \tau \leq T\right\}\right. \\
& +\operatorname{Tp}(s) \max \left\{\left|k_{1}(t, \tau)-k_{1}(s, \tau)\right| v_{1}(\tau): 0 \leq \tau \leq T\right\}
\end{align*}
\]
and
\[
\begin{align*}
& p(s)\left\|\int_{0}^{t} k_{1}(t, \tau) f_{1}(\tau, x(\tau)) d \tau\right\|_{L^{2}} \leq|t-s| p(s)  \tag{3.12}\\
& \cdot\left(r \cdot \max \left\{k_{1}(t, \tau)\left(u_{1}(\tau) / p(\tau)\right): 0 \leq \tau \leq T\right\}\right. \\
& \left.+\max \left\{k_{1}(t, \tau) v_{1}(\tau): 0 \leq \tau \leq T\right\}\right)
\end{align*}
\]

Now using (i), (iv) and (3.1) for \(i=2\), we have the following estimates
(3.13) \(|p(t)-p(s)|\left\|\int_{0}^{\infty} k_{2}(t, \tau) f_{2}(\tau, x(\tau)) d \tau\right\|_{L^{2}}\)
\[
\begin{aligned}
& \leq|p(t)-p(s)| \cdot\left(\int_{0}^{\infty} k_{2}(t, \tau)\left(u_{2}(\tau) / p(\tau)\right) d \tau\right. \\
& \left.+\int_{0}^{\infty} k_{2}(t, \tau) v_{2}(\tau) d \tau\right) \leq \max \left\{\frac{1}{p(t)}: 0 \leq t \leq T\right\}|p(t)-p(s)|(M r+B)
\end{aligned}
\]

Now wr mote that
\[
\int_{0}^{\infty} k_{2}(t, \tau)-k_{2}(s, \tau)\left\|f_{2}(\tau, x(\tau))\right\|_{L^{2}} d \tau<\infty
\]

Indeed, we have
\[
\begin{aligned}
& p(s) \int_{0}^{\infty}\left|k_{2}(t, \tau)-k_{2}(s, \tau)\right|\left\|f_{2}(\tau, x(\tau))\right\|_{L^{2}} d \tau \\
& \leq p(s)\left(r \int_{0}^{\infty} k_{2}(t, \tau)\left(u_{2}(\tau) / p(\tau)\right) d \tau+\int_{0}^{\infty} k_{2}(t, \tau) v_{2}(\tau) d \tau\right. \\
& \left.+r \int_{0}^{\infty} k_{2}(s, \tau)\left(u_{2}(\tau) / p(\tau)\right) d \tau+\int_{0}^{\infty} k_{2}(s, \tau) v_{2}(\tau) d \tau\right) \\
& \leq p(s) 2 \cdot \max \{1 / p(t): 0 \leq t \leq T\}(M r+B)
\end{aligned}
\]

By the estimate given above, for any given \(\delta>0\) and sufficiently large \(T\) we have
\[
\begin{align*}
& p(s) \int_{J_{0}}^{\infty}\left|k_{2}(t, \tau)-k_{2}(s, \tau)\right|\left\|f_{2}(\tau, s(\tau))\right\|_{L^{2}} d \tau  \tag{3.14}\\
& \leq p(s)\left(r \int_{0}^{T}\left|k_{2}(t, \tau)-k_{2}(s, \tau)\right|\left(u_{2}(\tau) / p(\tau)\right) d \tau\right. \\
& \left.+\int_{0}^{T}\left|k_{2}(t, \tau)-k_{2}(s, \tau)\right| v_{2}(\tau) d \tau\right)+p(s) \cdot \\
& \cdot \int_{T}^{\infty}\left|k_{2}(t, \tau)-k_{2}(s, \tau)\right|\left\|f_{2}(\tau, x(\tau))\right\|_{L^{2}} d \tau \\
& \leq \max \left\{k_{2}(t, \tau)-k_{2}(s, \tau): 0 \leq \tau \leq T\right\} \cdot \max \left\{k_{2}(t, \tau)^{-1}:\right. \\
& 0 \leq \tau \leq T\}\left(r p(s) \int_{0}^{T} k_{2}(t, \tau)\left(u_{2}(\tau) / p(\tau)\right) d \tau\right. \\
& \left.+p(s) \int_{0}^{T} k_{2}(t, \tau) v_{2}(\tau) d \tau\right)+\sup \{p(s): 0 \leq s \leq T\} \\
& \cdot \int_{T}^{\infty}\left|k_{2}(t, \tau)-k_{2}(s, \tau)\right|\left\|f_{2}(\tau, x(\tau))\right\|_{L^{2}} d \tau \\
& \leq \max \left\{k_{2}(t, \tau)-k_{2}(s, \tau): 0 \leq \tau \leq T\right\} \cdot \max \left\{k_{2}(t, \tau)^{-1}:\right. \\
& 0 \leq \tau \leq T\} \sup \{p(s) / p(t): s, t \in[0, T], s \leq t\}(M r+B) \\
& +\sup \{p(s): 0 \leq s \leq T\} \cdot \int_{T}^{\infty}\left|k_{2}(t, \tau)-k_{2}(s, \tau)\right| \\
& \cdot\left\|f_{2}(\tau, x(\tau))\right\|_{L^{2}} d \tau \leq C(T)(M r+B)+\delta,
\end{align*}
\]
where \(C(T)\) is a positive constant.
We need to recall the definition of the modulus of continnity which is defined for all real functions \(w\) as:
\[
\begin{equation*}
\nu_{T}(u ; \varepsilon)=\sup \{|w(t)-u(s)|: t, s \in[0, T] .|t-s| \leq=\} . \quad z>0 . \tag{3.15}
\end{equation*}
\]

Using now (3.15), the properties of the functions \(k_{1}, k_{2}\) and \(p\) we have
\[
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \nu_{T}\left(k_{1} ; \varepsilon\right)=\lim _{\varepsilon \rightarrow 0} \nu_{T}\left(k_{2} ; \varepsilon\right)=\lim _{\varepsilon \rightarrow 0} \nu_{T}(p ; \varepsilon)=0 \tag{3.16}
\end{equation*}
\]

Moreover, by the assumption (iii) and (v), we see that
\[
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \nu_{T}\left(\|h(t, x(t))-h(s, x(s))\|_{L^{2}} ; \varepsilon\right)=0 \tag{3.17}
\end{equation*}
\]

Therefore, by (3.9)-(3.14) and (3.16), (3.17), we get for \(U \subset V(0, r)\)
\[
\begin{equation*}
\beta_{0}(H U)=0 \tag{3.18}
\end{equation*}
\]

Fix now \(U \subset V(0, r), r=B /(1-M)\). We prove that
\[
\begin{equation*}
a(H U) \leq M a(U) \tag{3.19}
\end{equation*}
\]

It is clear, by the definition of the integral, that for any given \(\eta_{1}>0\) there exists a positive integer \(n_{1}=n_{1}\left(\eta_{1}\right)\) such that for \(n \geq n_{1}\)
\[
\begin{aligned}
& \mid \int_{0}^{t} k_{1}(t, \tau)\left(u_{1}(\tau)\|x(\tau)\|_{L^{2}} / p(\tau)\right) p(\tau) d \tau \\
& \left.-\sum_{k=0}^{n-1} \frac{t}{n} k_{1}\left(t, \frac{k t}{n}\right)\left(u_{1}\left(\frac{k t}{n}\right)\left\|\left(\frac{k t}{n}\right)\right\|_{L^{2}} / p\left(\frac{k t}{n}\right)\right) p\left(\frac{k t}{n}\right) \right\rvert\,<\eta_{1} .
\end{aligned}
\]

Let now \(T<t\). Put \(k_{1}^{*}=\max \left\{k: 0 \leq k \leq n, \frac{k t}{n}<T\right\}\), then we have
\[
\begin{aligned}
& \int_{0}^{t} k_{1}(t, \tau)\left(u_{1}(\tau)\|x(\tau)\|_{L^{2}} / p(\tau)\right) p(\tau) d \tau \\
& \leq \eta_{1}+\sum_{k=0}^{k_{i}^{i}} \frac{t}{n} k_{1}\left(t, \frac{k t}{n}\right)\left(u_{1}\left(\frac{k t}{n}\right)\left\|\left(\frac{k t}{n}\right)\right\|_{L^{2}} / p\left(\frac{k t}{n}\right)\right) p\left(\frac{k t}{n}\right) \\
& +\sum_{k=k_{i}^{i}+1}^{n-1} \frac{t}{n} k_{1}\left(t, \frac{k t}{n}\right)\left(u_{1}\left(\frac{k t}{n}\right)\left\|\left(\frac{k t}{n}\right)\right\|_{L^{2}} / p\left(\frac{k t}{n}\right)\right) p\left(\frac{k t}{n}\right) \\
& =\eta_{1}+I_{1}+I_{2}
\end{aligned}
\]

Now for any given \(\eta_{2}>0\) there exists \(n_{2}=n\left(\eta_{2}\right)\) such that for \(n \geq n_{2}\)
\[
\begin{aligned}
I_{1} \leq & k_{1} t \cdot \max \left\{p\left(\frac{k t}{n}\right)\left\|\left(\frac{k t}{n}\right)\right\|_{L^{2}}: \frac{k t}{n}<T\right\} \max \left\{k_{1}(t, \tau)\right. \\
& \left.\left(u_{1}(\tau) / p(\tau)\right): 0 \leq \tau \leq T\right\} n^{-1}<\eta_{2}
\end{aligned}
\]

Similarly, for any given \(\eta_{3}>0\)
\[
I_{2} \leq \sup \left\{p(t)\|x(t)\|_{L^{2}}: t \geq T\right\}\left(\int_{0}^{t} k_{1}(t, \tau)\left(u_{1}(\tau) / p(\tau)\right) d \tau+\eta_{3}\right)
\]
for sufficiently large \(n\).
We put
\[
\begin{aligned}
& g_{t}(\tau)=k_{1}(t, \tau)\left(u_{2}(\tau) / p(\tau)\right) \\
& g_{t}^{*}(\tau)=g(\tau, t)\|x(\tau)\|_{L^{2}} p(\tau), \text { where } t \in \mathbf{R}_{+}, x \in V(0, r) .
\end{aligned}
\]

By the assumption of Theorem 3.1 we get
\[
\int_{0}^{\infty} g_{t}(\tau) d \tau<\infty, \quad \int_{0}^{\infty} g_{t}^{*}(\tau) d \tau<\infty \quad \text { for } t \in \mathbf{R}_{+}
\]

This fact allows us to find functions \(\tilde{g}_{i}, \tilde{g}_{t}^{*}\) which are nonnegative decreasing and
\[
\lim _{\tau \rightarrow \infty} \tilde{g}_{t}(\tau)=\lim _{\tau \rightarrow \infty} \tilde{g}_{t}^{*}(\tau)=0
\]

These functions satisfy additionally the following conditions:
\[
g_{t}(\tau) \leq \tilde{g}_{t}(\tau), \quad g_{t}^{*}(\tau) \leq \tilde{g}_{t}^{*}(\tau)
\]
and
\[
\int_{0}^{\infty} \tilde{g}_{t}(\tau) d \tau<\infty, \quad \int_{0}^{\infty} \tilde{g}_{t}^{*}(\tau) d \tau<\infty
\]

Hence, we ćan write
\[
\int_{0}^{\infty} \widetilde{g}(\tau) d \tau=\lim _{h \rightarrow 0_{+}} h \sum_{n=1}^{\infty} \tilde{g}_{i}(n h)
\]
and
\[
\int_{0}^{\infty} \tilde{g}_{i}^{*}(\tau) d \tau=\lim _{h \rightarrow 0_{+}} h \sum_{n=1}^{\infty} \tilde{g}_{i}^{*}(n h) \quad(\text { see }[15])
\]

Moreover, \(\tilde{g}_{t}(\tau)\) can be choosen such that
\[
\lim _{0<h \rightarrow 0} h\left|\sum_{n=1}^{\infty} \tilde{g}_{t}(n h)-\sum_{n=1}^{\infty} g_{t}(n h)\right|=0
\]
and
\[
\lim _{0<h \rightarrow 0} h\left|\sum_{n=1}^{\infty} \hat{g}_{t}^{\prime}(n h)-\sum_{n=1}^{\infty} g_{t}^{*}(n h)\right|=0
\]

Let \(T>0\) be fixed. Choose \(m\) such large that \(m+1>T\). Then, by the assumptions,
we have
\[
\begin{aligned}
& p(t)\left\|\int_{0}^{\infty} k_{2}(t, \tau) f_{2}(t, x(\tau)) d \tau\right\|_{L^{2}} \leq p(t) \int_{0}^{\infty} g_{i}^{*}(\tau) d \tau \\
& +p(t) \int_{0}^{\infty} k_{2}(t, \tau) \cdot v_{2}(\tau) d \tau \leq p(t)\left|\int_{0}^{\infty} \tilde{g}_{i}^{*}(\tau) d \tau-h \sum_{n=1}^{\infty} \vec{g}_{t}(n h)\right| \\
& +p(t) h\left|\sum_{n=1}^{\infty} \tilde{g}_{t}^{*}(n h)-\sum_{n=1}^{\infty} g_{t}^{*}(n h)\right|+p(t) h \sum_{n=1}^{\infty} g_{t}^{*}(n h) \\
& +p(t) \int_{0}^{\infty} k_{2}(t, \tau) \cdot v_{2}(\tau) d \tau \leq p(t)\left|\int_{0}^{\infty} g_{l}^{*}(\tau) d \tau \cdots h \sum_{n=1}^{\infty} \tilde{g}_{t}^{*}(n h)\right| \\
& +p(t) h\left|\sum_{n=1}^{\infty} \tilde{g}_{t}^{*}(n h)-\sum_{n=1}^{\infty} g_{t}^{*}(n h)\right|+p(t) h r \sum_{n=1}^{m} g_{t}(n h) \\
& +p(t) \sup \left\{\|x(n h)\|_{L^{2}}^{2} p(n h): n \geq m+1\right\} h . \sum_{n=n+1}^{\infty} g_{t}(n h) \\
& +p(t) \int_{0}^{\infty} k_{2}(t, \tau) v_{2}(\tau) d \tau .
\end{aligned}
\]

Letting now \(h \rightarrow 0\), we have
\[
\begin{aligned}
& p(t)\left\|\int_{0}^{\infty} k_{2}(t, \tau) f_{2}(\tau, x(\tau)) d \tau\right\|_{L^{2}} \leq \sup \left\{p(t)\|x(t)\|_{L^{2}}: t \geq T\right\} \\
& \left.+p(t) \int_{0}^{\infty} g_{t}(\tau) d \tau\right)+p(t) \int_{0}^{\infty} k_{2}(t, \tau) v_{2}(\tau) d \tau
\end{aligned}
\]

By (iii), we have
\[
p(t)\|h(t, x(t))\|_{L^{2}} \leq k \cdot \sup \left\{p(t)\|x(t)\|_{L^{2}}: t \geq T\right\}+p(t) \mid h(t, 0) \|
\]

Therefore, by the above considerations, we get
\[
\begin{aligned}
& p(t)\|(H x)(t)\|_{L^{2}} \leq p(t)|h(t, 0)|+M \cdot \sup \left\{p(t)\|x(t)\|_{L^{2}}: t \geq T\right\} \\
& +p(t)\left(\eta_{1}+\eta_{2}+r \eta_{3}\right)+p(t)\left(\int_{0}^{t} k_{1}(t, \tau) v_{1}(\tau) d \tau+\int_{0}^{\infty} k_{2}(t, \tau) v_{2}(\tau) d \tau\right)
\end{aligned}
\]

Thus, by the assumptions of Theorem 3.1, we obtain
\[
\begin{aligned}
& \lim _{T \rightarrow \infty} \sup _{x \in U}\left\{\sup \left\{p(t)\|(H x)(t)\|_{L^{2}}: t \geq T\right\}\right\} \leq\left(\eta_{1}+\eta_{2}+r \eta_{3}\right) C_{1} \\
& +M \cdot \lim _{T \rightarrow \infty} \sup _{x \in U}\left\{\sup \left\{p(t)\|x(t)\|_{L^{2}}: t \geq T\right\}\right\}
\end{aligned}
\]

Let now \(\eta_{i} \rightarrow 0, i=1,2,3\). Then we get (3.19). Finally, by (3.18), (3.19) and the assumptions (viii) we obtain
\[
\mu_{0}(H U) \leq D \cdot \mu_{0}(U)
\]
where \(D=\max \left\{L_{1}+L_{2}+L_{3}, M\right\}\), which proves that \(H\) is a \(\mu_{0}\)-contraction. This fact by Theorem 2.1 ends the proof.
4. Remarks. In the monograph [13] the authors study the stochastic integral equation of the Fredholm type of the form
\[
\begin{equation*}
x(t ; \omega)=h(t, x(t ; \omega))+\int_{0}^{\infty} k(t, \tau ; \omega) f(\tau, x(\tau ; \omega)) d \tau \tag{4.1}
\end{equation*}
\]
(a) Theorem (3.1) extends the following result of Theorem 4.5 .3 gven in [13].

Theorem 4.1. ([9], [13] p.125). Consider the random integral equation (4.1) subject the following condtions:
(i) \(H_{1}\) and \(H_{2}\) are Hilbert spaces stronger than \(C_{c}\) and the pair \(\left(H_{1}, H_{2}\right)\) is admissible with respect to the completely continuous integral operator
\[
(W x)(t ; \omega)=\int_{0}^{\infty} k(t, \tau ; \omega) x(\tau ; \omega) d \tau, \quad t \in \mathbf{R}_{+}
\]
where \(k(t, \tau ; \omega)\) behaves as described previously and the integral
\[
\int_{0}^{\infty} \int_{0}^{\infty} k(t, \tau) d \tau d t
\]
exists and is finite;
(ii) \(x(; \omega) \rightarrow f(t, x(t ; \omega))\) is a continuous operator on
\[
S=\left\{x(t ; \omega): x(t ; \omega) \in H_{1},\|x(t ; \omega)\|_{H_{1}} \leq \rho\right\}
\]
for some \(\rho>0\) with values in \(H_{2}\) such that \(\|f(t, x(t ; \omega))\|_{H_{2}} \leq \gamma\) for some \(\gamma>0\) a constant;
(iii) \(x(t ; \omega) \rightarrow h(t, x(t ; \omega))\) is the contraction on \(S\).

Then there exists at least one bounded (by \(\rho\) ) random solution of equation (4.1) provided
\[
\|h(t, x(t ; \omega))\| H_{1}+\gamma K \leq \rho,
\]
where \(K\) is the norm of the operator \(W\).
We see that the assumptions (i)-(iii) of Theorem imply the conditions (i)-(viii) of Theorem 3.1 if we put \(p(t) \equiv 1\) for \(t \in \mathbf{R}_{+}, u_{i}(t) \equiv 0, i=1,2\) and \(v_{1}(t) \equiv 0\), \(v_{2}(t) \equiv \gamma\) for \(t \in \mathbf{R}_{+}\).

Analogonsly, we prove that Theorem 3.1 generalizes the Theorems 4.5, 4.5.4, and 4.5.6 of [13].
(b) The proof of Theorem 3.1 can be extended to the case when \(x(\cdot ; \omega) \in\) \(L_{p}(\Omega, \mathcal{A} P)\).
(c) If \(\mu^{\prime}() \equiv 1\) then a random solution \(x(t ; \omega)\) of (1.1) is asymptotically stable in the sense of Deffintion 2.2 .
5. Example. First we give examples functions which are sublinear, but they do not satisfy the Lipschiz condition.

Lemına 1. If a real function satisfies the Lipschitz condition and it is differentiable then the derivative is bounded.

We onit the proof.
Example 5.1. Let \(f: \mathbf{R}_{+} \rightarrow \mathbf{R}\) be defined as follows:
\[
f(x)=x \cdot \exp (\sin x)
\]

We see that
\[
|f(x)| \leq e \cdot|x| \quad \text { for } \quad x \in \mathbf{R}_{+} \text {, }
\]
and
\[
f^{\prime}(x)=\exp (\sin x)+x \cdot \cos x \cdot \exp (\sin x)
\]

Hence, by Lemma 5.1, the function \(f\) does not satisfy the Lipschitz condition.
Example 5.2. Let \(f: \mathbf{R}_{+} \rightarrow \mathbf{R}\) be defined as follows:
\[
f(x)=(x-n+1)^{n}+n-1 \text { for } x \in[n-1, n),
\]
where \(n \in \mathcal{N}\).
It is clear that
\[
x-n+1 \geq(x-n+1)^{n} \quad \text { for } \quad x \in[n-1, n), \text { where } n \in \mathcal{N} .
\]

By the above inequality we have
\[
|f(x)| \leq|x| \quad \text { for } \quad x \in \mathbf{R}_{+}
\]

Moreover,
\[
f^{\prime}(x)=n(x-n+1)^{n-1} \text { for } x \in[n-1, n) \text {, where } n \in \mathcal{N} \text {. }
\]

By Lemma 5.1 the function \(f\) does not satisfy the Lipschitz condition.
Using the functions of Example 5.1, and 5.2 one can prove the following result.
Theorem 5.1. Let in the equation (1.1)
\[
\begin{aligned}
& f_{1}(t, x(; \omega))=x(t ; \omega) \exp (\sin [x(t ; \omega)]) \\
& f_{2}(t, x(t ; \omega))=(x(t ; \omega)-n+1)^{n}+n-1, \quad x(t ; \omega) \in[n-1, n)
\end{aligned}
\]
where \(n \in \mathcal{N}\), and
\[
h(t, x(t ; \omega)) \equiv h(t ; \omega)
\]

Suppose that
(i) \(k_{1}(t, \tau) \leq \tilde{k}_{1}(t) \bar{k}_{1}(\tau) \quad, \quad k_{2}(t, \tau) \leq \tilde{k}_{1}(t) \bar{k}_{2}(\tau)\), where \(\breve{k}_{1}, k_{1}, k_{2}\) are positive functions and \(\widetilde{k}_{1}\) is differentiable function;
(ii) \(D_{1}(t):=p(t) \tilde{k}_{1}(t)\left(\int_{0} t\left(\bar{k}_{1}(\tau) / p(\tau)\right) d \tau+\int_{0}^{t}\left(\bar{k}_{2}(\tau) / p(\tau)\right) d \tau\right)\) positive, differentiable and \(D_{2}=\sup \left\{D_{1}(t): t \in \mathbf{R}_{+}\right\}, \quad D_{2} \in[0,1)\);
(iii) \(D_{1}(0)=\widetilde{k}_{1}(0) \int_{0}^{\infty} \bar{k}_{2}(\tau) d \tau\),
and
\(\int_{0}^{\infty}\left(\bar{k}(\tau) / D_{2}(\tau)\right) \exp \left(\int_{0}^{\tau}\left(e \bar{k}_{1}\left(\tau_{1}\right) \widetilde{k}_{1}^{2}\left(\tau_{1}\right)+\widetilde{k}_{1}^{\prime}\left(\tau_{1}\right) D_{1}\left(\tau_{1}\right)\right) \cdot\left(D_{1}\left(\tau_{1}\right) \widetilde{k}_{1}\left(\tau_{1}\right)\right)^{-1} d \tau_{1}\right) d \tau<\infty ;\)
(iv) \(\lim _{t \rightarrow \infty} p(t)\|x(t)-y(t)\|_{L^{2}}=0\)
uniformly with respect to \(x\) and \(y\) belonging to \(V(0, r)\), where \(r=\|h\|_{p} /\left(1-D_{2}\right)\);
(v) \(\lim _{i \rightarrow \infty} p(t)\|h(t)\|_{L^{2}}=0 ;\)
(vi) there exists \(L_{i}\) for \(i=1,2\) satisfying \(0 \leq L_{1}+L_{2}<1\) such that
\[
\begin{gathered}
m\left(\int_{0}^{t} k_{1}(, \tau ; \omega) f_{1}(\tau, U(\tau)) d \tau\right) \leq L_{1} m(U(t)) \\
m\left(\int_{0}^{\infty} k_{2}(t, \tau ; \omega) g f_{2}(\tau, U(\tau)) d \tau\right) \leq L_{2} m(U(t)), \text { where } L_{1}, L_{2} \in[0,1) \\
U(t)=\left\{x(s) \in L^{2}(\Omega, \mathcal{A}, P), s \geq 0, x \in U \subset V(0, r): p(t)\|x(t)\|_{2} \leq\|U\|_{p}\right\}, \\
t \geq 0, r=\|h\|_{p} /\left(1-D_{2}\right) .
\end{gathered}
\]

Then there exists at least one solution \(x \in C_{p}\) of equation (1.1) such that \(\|x(t)\|_{L^{2}}=o\left(\left(1 / D_{1}(t)\right) \exp \left(\int_{0}^{t}\left(\left(e k_{1}(\tau) \tilde{k}_{1}^{2}(\tau)+\widetilde{k}_{1}^{\prime}(\tau) D_{1}(\tau)\right) \cdot\left(D_{1}(\tau) \tilde{k}_{1}(\tau)\right)^{-1} d \tau\right)\right)\right.\).

Proof. By differentiating \(D_{1}(t)\) we obtain
\[
\left.\left.p(t)=D_{1}(t) \exp -\left(\int_{0}^{t}\left(\left(e \bar{k}_{1}(\tau) \tilde{k}_{1} 2(\tau)+\widetilde{k}_{1}^{\prime}(\tau) D_{1}(\tau)\right) / D_{1}(\tau)\right) \cdot \tilde{k}_{1}(\tau)\right)\right) d \tau\right)
\]

Hence, using Theorem 3.1 we get the statement of Theorem 5.1.

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\section*{STRESZCZENIE}

W pracy bada się losowe równanie Volterry-Fredholma postaci:
\[
\begin{aligned}
x(t ; \omega) & =h(t, x(t, \omega))+\int_{0}^{t} k_{1}(t, \tau ; \omega) f_{1}(\tau, x(\tau ; \omega)) d \tau \\
& +\int_{0}^{\infty} k_{2}(t, \tau ; \omega) f_{2}(\tau, x(\tau ; \omega)) d \tau
\end{aligned}
\]
przy slabszych zalożeniach niż rozważane w pracach [9] i [10]. Zakładamy jedynie, ze \(f_{1}\) i \(f_{2}\) sa funkcjami subliniowymi.```

