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**On the First Order Natural Operators Transforming 1-forms
on Manifold to the Tangent Bundle**

O operatorach naturalnych pierwszego rzędu transformujących
1-formy na rozmaiłości do wiązki stycznzej

Abstract. In this paper all first order natural operators transforming 1-forms on a manifold to tangent bundle, are determined. Fundamental operators of this type are a complete lift and a vertical lift of a 1-form. All first order natural operators form a 3-parameter family with coefficients being smooth functions of one variable.

The aim of this paper is to determine all first order natural operators transforming 1-forms on a manifold to the tangent bundle.

We deduce that the fundamental operator here are a complete lift and a vertical lift of a 1-form.

In the paper we use an invariant function theorem developed by I. Kolář, [2].

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1. Let M be a smooth n -dimensional manifold. We denote by $p_M : TM \rightarrow M$ a tangent bundle and by $q_M : T^*M \rightarrow M$ a cotangent bundle.

A classical field of 1-forms ω on the manifold M can be interpreted as a linear map $\omega : TM \rightarrow R$ with respect to the vector bundle structure $p_M : TM \rightarrow M$. If a 1-form ω has in a local chart (U, x^i) on M the local expression $\omega = b_i(x)dx^i$, then the linear map $\omega : TM \rightarrow R$ in a local induced chart $(p_M^{-1}(U), x^i, X^i)$ on TM is of the form $\omega = b_i(x)X^i$.

Consider the tangent map $T\omega : TTM \rightarrow TR = R \times R$. The second component of the tangent map $\Omega = pr_2 \circ T\omega$, where $pr_2 : R \times R \rightarrow R$ is a projection on the second factor, defines a linear map $\Omega = pr_2 \circ T\omega : TTM \rightarrow R$ with respect to the vector bundle structure $p_{TM} : TTM \rightarrow TM$.

Definition 1. A field of 1-forms Ω on TM defined by the second component of the tangent map $T\omega$, i.e.

$$(1.1) \quad \Omega = pr_2 \circ T\omega : TTM \rightarrow R$$

is called a complete lift of a field of 1-forms ω on M .

Definition 2. A field of 1-forms Ω on TM defined as the image of a field of 1-forms ω on M under a dual map p_M^* of the projection $p_M : TM \rightarrow M$, i.e.

$$(1.2) \quad \Omega = p_M^* \omega = \omega \circ T p_M : TTM \rightarrow R$$

is called a vertical lift of a field of 1-forms ω on M .

If a field of 1-forms ω on M has in a local chart (U, x^i) a local expression $\omega = b_i(x) dx^i$, then the complete lift $\Omega = \omega^c$ and the vertical lift $\Omega = \omega^v$ in the local induced chart $p_M^{-1}(U), x^i, X^i$ on TM are of the form

$$(1.3) \quad \omega^c = b_{ij} X^i dx^j + b_i dX^i$$

$$(1.4) \quad \omega^v = b_i dx^i.$$

If $\tau_M : TTM \rightarrow TTM$ is a canonical involution, then we have a field of 1-forms $\omega^c \circ \tau_M$ on TM

$$(1.5) \quad \omega^c \circ \tau_M = b_{ji} X^i dx^j + b_i dX^i$$

We need the following invariant function theorem developed by I. Kolář, [2].

Theorem 1. Let $f : R^n \times \dots \times R^n \times R^{n \cdot} \times \dots \times R^{n \cdot} \rightarrow R$ be a smooth and k -times l -times $Gl(n, R)$ invariant map. Then there exists a smooth function $\varphi : R^{k+l} \rightarrow R$ such that

$$(1.6) \quad f(x_i, y^p)_{\substack{i=1, \dots, l \\ p=1, \dots, k}} = \varphi((x_i, y^p))_{\substack{i=1, \dots, l \\ p=1, \dots, k}}.$$

We will use the following

Lemma 2. Every $Gl(n, R)$ invariant smooth map $G : R^n \times R^n \times R^{n \cdot} \times \otimes^2 R^{n \cdot} \rightarrow R$ is of the form

$$(1.7) \quad G(y^i, X^i, b_i, b_{ij}) = \psi(y^i b_i, X^i b_i, y^i y^j b_{ij}, y^i X^j b_{ij}, X^i y^j b_{ij}, X^i X^j b_{ij}),$$

where $\psi : R^6 \rightarrow R$ is a smooth function.

Proof. Consider any $Gl(n, R)$ invariant smooth map $\tilde{G} : R^n \times R^n \times R^{n \cdot} \times R^{n \cdot} \times R^{n \cdot} \rightarrow R$ such that $\tilde{G} = G \circ \otimes$, i.e.

$$(1.8) \quad \tilde{G}(y^i, X^i, b_i, u_i, v_i) = G(y^i, X^i, b_i, u_i, v_i).$$

By the invariant function theorem there exists a smooth function $\varphi : R^6 \rightarrow R$ such that

$$(1.9) \quad \tilde{G}(y^i, X^i, b_i, u_i, v_i) = \varphi(y^i b_i, y^i u_i, y^i v_i, X^i b_i, X^i u_i, X^i v_i).$$

Taking into account the invariance with respect to $u_i \mapsto k \cdot u_i$, $v_i \mapsto \frac{1}{k} \cdot v_i$ for $k \in R \setminus \{0\}$, we obtain the relation

$$(1.10) \quad \varphi(\alpha, \beta, \gamma, \delta, \varepsilon, \omega) = \varphi(\alpha, k \cdot \beta, \frac{1}{k} \cdot \gamma, \delta, k \cdot \varepsilon, \frac{1}{k} \cdot \omega) .$$

By the invariant function theorem for $n=1$, there exists a smooth function $\psi : R^4 \rightarrow R$ depending on two parameters α, δ such that

$$(1.11) \quad \varphi(\alpha, \beta, \gamma, \delta, \varepsilon, \omega) = \psi(\alpha, \delta, \beta \cdot \gamma, \beta \cdot \omega, \varepsilon \cdot \gamma, \varepsilon \cdot \omega) .$$

Thus, we obtain

$$(1.12) \quad G(y^i, X^i, b_i, u_i \cdot v_j) = \psi(y^i b_i, X^i b_i, y^i y^j u_i v_j, y^i X^j u_i v_j, X^i y^j u_i v_j, X^i X^j u_i v_j) .$$

This proves the lemma, if we put $b_{ij} = u_i \cdot v_j$.

2. In this part we determine all first order natural operators transforming 1-forms on manifold M to the tangent bundle TM .

Theorem 3. All first order natural operators $F : T^*M \rightarrow T^*TM$ set up a 3-parameter family of the form

$$(2.1) \quad F : b_i dx^i \mapsto a(b_k X^k)[b_i dx^i] + b(b_k X^k)[b_{ij} X^j dx^i + b_i dX^i] + c(b_k X^k)[b_{ji} X^j dx^i + b_i dX^i] ,$$

where a, b, c are three arbitrary smooth functions of one variable.

Proof. Any map $F : T^*M \rightarrow T^*TM$ in local coordinates (x^i) on M and (x^i, X^i) on TM is of the form

$$(2.2) \quad F : b_i(x) dx^i \mapsto e_i(x^k, X^k) dx^i + g_i(x^k, X^k) dX^i .$$

The first order natural operators $F : T^*M \rightarrow T^*TM$ are in bijection with natural transformations $F : J^1 T^*M \rightarrow T^*TM$ and L_n^2 -equivariant maps of standard fibres $F : (J^1 T^*R^n)_0 \rightarrow (T^*TR^n)_0$.

The group L_n^2 acts on the standard fibre $S = (J^1 T^*R^n)_0$ in the form

$$(2.3) \quad \begin{aligned} \bar{b}_i &= b_j \tilde{a}_i^j \\ \bar{b}_{ij} &= b_{kl} \tilde{a}_i^k \tilde{a}_j^l + b_k \tilde{a}_i^k . \end{aligned}$$

We denote by $(\tilde{a}_j^i, \tilde{a}_{jk}^i)$ the coordinates of the inverse element a^{-1} of an element $a \in L_n^2$ with coordinates (a_j^i, a_{jk}^i) .

The group L_n^2 acts on the standard fibre $W = (T^*TR^n)_0$ by formula

$$(2.4) \quad \begin{aligned} \bar{X}^i &= a_j^i X^j \\ \bar{e}_i &= e_j \tilde{a}_i^j + g_k \tilde{a}_{li}^k a_j^l X^j \\ \bar{g}_i &= g_j \tilde{a}_i^j . \end{aligned}$$

Any map $F : (J^1 T^* R^n)_0 \rightarrow (T^* T R^n)_0$ in coordinates (b_i, b_{ij}) and (X^i, e_i, g_i) is of the form

$$(2.5) \quad \begin{aligned} e_i &= e_i(X^i, b_i, b_{ij}) \\ g_i &= g_i(X^i, b_i, b_{ij}) . \end{aligned}$$

Our aim is to find a general form of an L_n^2 -equivariant smooth maps $e_i : R^n \times R^{n \cdot} \times \otimes^2 R^{n \cdot} \rightarrow R^{n \cdot}$ and $g_i : R^n \times R^{n \cdot} \times \otimes^2 R^{n \cdot} \rightarrow R^{n \cdot}$.

We define an L_n^1 -invariant smooth map $G : R^n \times R^n \times R^{n \cdot} \times \otimes^2 R^{n \cdot} \rightarrow R$ by formula

$$(2.6) \quad G(y^i, X^i, b_i, b_{ij}) = g_i(X^i, b_i, b_{ij}) \cdot y^i .$$

Considering equivalence with respect to homotheties $y^i \mapsto ky^i$ of L_n^1 -invariant map $G = g_i y^i$ of the form (1.7), we get

$$(2.7) \quad \begin{aligned} \psi(ky^i b_i, X^i b_i, k^2 y^i b_{ij}, ky^i X^j b_{ij}, kX^i y^j b_{ij}, X^i X^j b_{ij}) = \\ = k \cdot \psi(y^i b_i, X^i b_i, y^i y^j b_{ij}, y^i X^j b_{ij}, X^i y^j b_{ij}, X^i X^j b_{ij}) . \end{aligned}$$

From this, the map ψ is linear in $y^i b_i$, $y^i X^j b_{ij}$, $X^i y^j b_{ij}$ and is independent of $y^i y^j b_{ij}$, where coefficients are three arbitrary smooth functions p, q, r of two variables depending on $b_i X^i$ and $b_{ij} X^i X^j$.

Thus, every L_n^1 -invariant map $g_i : R^n \times R^{n \cdot} \times \otimes^2 R^{n \cdot} \rightarrow R^{n \cdot}$ is of the form

$$(2.8) \quad \begin{aligned} g_i(X^k, b_k, b_{kl}) = p(b_k X^k, b_{kl} X^k X^l) b_i + q(b_k X^k, b_{kl} X^k X^l) b_{ij} X^j + \\ + r(b_k X^k, b_{kl} X^k X^l) b_{ji} X^j \end{aligned}$$

with arbitrary smooth function p, q, r of two variables. In the same way, we obtain L_n^1 -invariant map $e_i : R^n \times R^{n \cdot} \times \otimes^2 R^{n \cdot} \rightarrow R^{n \cdot}$ of the form

$$(2.9) \quad \begin{aligned} e_i(X^k, b_k, b_{kl}) = a(b_k X^k, b_{kl} X^k X^l) b_i + b(b_k X^k, b_{kl} X^k X^l) b_{ij} X^j + \\ + c(b_k X^k, b_{kl} X^k X^l) b_{ji} X^j \end{aligned}$$

with arbitrary smooth functions a, b, c of two variables.

We will consider L_n^2 -equivariance of the map $F : (J^1 T^* R^n)_0 \rightarrow (T^* T R^n)_0$. If the map F is L_n^2 -equivariant, then for every vector $A = (A_j^i, A_{jk}^i)$ of the Lie algebra l_n^2 of L_n^2 the corresponding fundamental vector fields A_s on $S = (J^1 T^* R^n)_0$ and A_w on $W = (T^* T R^n)_0$ must be F -related. This gives the following system of partial differential equations for maps g_i and e_i with parameters A_j^i, A_{jk}^i :

$$(2.10) \quad \begin{aligned} -A_j^i g_j &= \frac{\partial p}{\partial u^2} (-b_k A_{lm}^k X^l X^m) b_i - p A_j^i b_j + \\ &+ \frac{\partial q}{\partial u^2} (-b_k A_{lm}^k X^l X^m) b_{ij} X^j - q b_{kl} A_j^k X^l - q b_k A_{ji}^k X^j + \\ &+ \frac{\partial r}{\partial u^2} (-b_k A_{lm}^k X^l X^m) b_{ij} X^j - r b_{kl} A_j^k X^l - r b_k A_{ji}^k X^j , \end{aligned}$$

$$(2.11) \quad \begin{aligned} -A_j^i e_j - A_{ji}^k X^j g_k &= \frac{\partial a}{\partial u^2} (-b_k A_{lm}^k X^l X^m) - a A_j^i b_j + \\ &+ \frac{\partial b}{\partial u^2} (-b_k A_{lm}^k X^l X^m) b_{ij} X^j - b b_{kl} A_j^k X^l - b b_k A_{ji}^k X^j + \\ &+ \frac{\partial c}{\partial u^2} (-b_k A_{lm}^k X^l X^m) b_{ji} X^j - c b_{kl} A_j^k X^l - c b_k A_{ji}^k X^j . \end{aligned}$$

First, we consider the differential equation (2.10). Setting $A_j^i = 0$ in (2.10), we obtain

$$(2.12) \quad \frac{\partial p}{\partial u^2} = 0 \quad , \quad \frac{\partial q}{\partial u^2} = 0 \quad , \quad \frac{\partial r}{\partial u^2} = 0$$

$$(2.13) \quad q + r = 0 .$$

By means of (2.12), we get that smooth functions p, q, r of two variables are independent of the second variable. Thus, the map $g_i : R^n \times R^n \times \otimes^2 R^n \rightarrow R^n$ is of the form

$$(2.14) \quad g_i(X^k, b_k, b_{kl}) = p(b_k X^k) b_i - q(b_k X^k) b_{ij} X^j - q(b_k X^k) b_{ji} X^j$$

Now, setting $A_j^i = 0$ in (2.11) and using (2.13), we obtain

$$(2.15) \quad \frac{\partial a}{\partial u^2} = 0 \quad , \quad \frac{\partial b}{\partial u^2} = 0 \quad , \quad \frac{\partial c}{\partial u^2} = 0$$

$$(2.16) \quad p = b + c \quad , \quad q = 0 .$$

By means of (2.15), we get that smooth functions a, b, c of two variables are independent of the second variable. Thus, the maps $e_i : R^n \times R^n \times \otimes^2 R^n \rightarrow R^n$ and $g_i : R^n \times R^n \times \otimes^2 R^n \rightarrow R^n$ are of the form

$$(2.17) \quad \begin{aligned} e_i(X^k, b_k, b_{kl}) &= a(b_k X^k) b_i + b(b_k X^k) b_{ij} X^j + c(b_k X^k) b_{ji} X^j \\ g_i(X^k, b_k, b_{kl}) &= [b(b_k X^k) + c(b_k X^k)] b_i . \end{aligned}$$

Finally, using (2.17) in (2.2), we obtain the 3-parameter system of natural operators of the form (2.1). This proves theorem.

The geometrical interpretation of the 3-parameter system (2.1) of first order natural operators $F : T^*M \rightarrow T^*TM$ is

$$F : \omega \mapsto a(b_i X^i) \cdot \omega^v + b(b_i X^i) \cdot \omega^c + c(b_i X^i) \cdot \omega^c \circ \tau_M$$

where ω^v and ω^c are the vertical lift and the complete lift of ω .

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STRESZCZENIE

W pracy wyznacza się wszystkie operatory naturalne pierwszego rzędu transformujące 1-formy na rozmaitości do wiązki stycznej. Podstawowymi operatorami tego typu są podniesienie zupełne i podniesienia wertykalne 1-formy. Wszystkie operatory naturalne pierwszego rzędu stanowią 3-parametrową rodzinę ze współczynnikami będącymi funkcjami gładkimi jednej zmiennej.

