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Local and Global Lipschitz Classes

Lokálne i globálne klasy Lipschitza

Локальные и глобальные классы Липшица

1. Introduction. A modulus of continuity is a concave positive increasing function $\eta : [0, \infty) \rightarrow \mathbb{R}$. Let D be a nonempty domain in \mathbb{R}^n . A function $u : D \rightarrow \mathbb{R}$ belongs to the global Lipschitz class $\text{Lip}_\eta(D)$ if there exists a constant $M < \infty$ such that

$$(1.1) \quad |u(x) - u(y)| \leq M \eta(x, y),$$

whenever x and y belong to the domain D ; here and later on $\eta(x, y) := \eta(|x - y|)$. We say that the function u belongs to the corresponding local Lipschitz class $\text{loc Lip}_\eta(D)$ if there exists constants $b \in (0, 1)$ and $M = M_b$ such that (1.1) holds for each $x \in D$ and $y \in B_b(x) := B(x, b \text{dist}(x, \partial D))$. As a matter of fact, in [L, Theorem 2.17 and 2.19] it is shown that it is equivalent to require that the condition holds for $b = 1/2$. And more generally, if a modulus of continuity η is "smooth" enough, then $u \in \text{loc Lip}_\eta(D)$ if and only if (1.1) holds whenever x and y belong to an open ball contained in D ; see [L, Theorem 4.29]. It should be remarked that

this definition differs from the standart definitions of local Hölder spaces. In fact, the class $\text{loc Lip}_\alpha(D)$ is not a local space but in some sense semiglobal.

In this paper we study the domains where local and global Lipschitz classes are equal. These domains are called Lip_α -extension domains. More generally, let h and g be two moduli of continuity. We say that the domain D is a $\text{Lip}_{h,g}$ -extension domain if there is a constant $E = E(D, h, g)$ such that every function u in the class $\text{loc Lip}_h(D)$ with a constant m , belongs also to the class $\text{Lip}_g(D)$ with a constant $M = Em$. We write Lip_α for the Hölder spaces, where $h(t) = t^\alpha$, $0 < \alpha \leq 1$.

For quasiconformal mappings and solutions of elliptic partial differential equations it is easy to derive local Lipschitz results and hence in $\text{Lip}_{h,g}$ -extension domains global Lipschitz bounds are obtained. See [GM1] and [GM2] for these applications. Some applications for Sobolev embedding theorems is found from [LL] and [Le]. Applications to analytic functions is presented in [GM1] and [L, Section 7].

2. $\text{Lip}_{h,g}$ -extension domains. Let h and g be two metrics in the domain $D \subset \mathbb{R}^n$. We say that g dominates h in D and write $h < g$ if there is a constant $A < \infty$ such that for each $x, y \in D$

$$h(x, y) \leq Ag(x, y) .$$

The modulus of continuity h defines in D the metric

$$(2.1) \quad h_D(x, y) := \inf_{\gamma(x, y)} \int_{\gamma} \frac{h(\text{dist}(\tau(s), \partial D))}{\text{dist}(\tau(s), \partial D)} ds ,$$

where $\gamma(x, y)$ is a rectifiable curve joining x to y in D and $\text{dist}(\gamma(s), \partial D)$ is the euclidean distance from the point $\gamma(s)$ (arc length representation for γ) to the boundary of the domain D .

For the proof of the following characterisation of $\text{Lip}_{h, g}$ -extension domains see [L, Theorem 3.6] or [GM2, Theorem 2.2].

Theorem 2.1. Let h and g be two moduli of continuity. A domain D is a $\text{Lip}_{h, g}$ -extension domain if and only if $h_D \prec g$.

Notice that if $h_D \prec g$ in D , then $h \prec g$ in D , see [L, Lemma 3.8].

Corollary 2.2. A domain D is a Lip_h -extension domain if and only if $h_D \prec h$.

The next inclusion theorem is proved in [L, Theorem 4.6].

Theorem 2.3. Let D be a Lip_h -extension domain and g a modulus of continuity such that the function h/g is decreasing. Then D is also a Lip_g -extension domain.

If $h(t) = t^\alpha$, $g(t) = t^\beta$ and $0 < \alpha < \beta \leq 1$ then every Lip_α -extension domain is also a Lip_β -extension domain, because the function $h(t)/g(t) = t^{\alpha-\beta}$ is decreasing. On the other hand, we can construct Lip_β -extension domains, which are not Lip_α -extension domains. For one construction see [L, Countexample 6.7].

Let us recall that a domain D in \mathbb{R}^n is c -quasiconvex if every $x, y \in D$ can be joined by a rectifiable curve γ in D with

$$l(\gamma) \leq c|x - y|,$$

where $l(\gamma)$ is the length of the curve γ .

Theorem 2.4. A $\text{Lip}_{h,g}$ -extension domain is quasiconvex.

Proof. Let $g(t) = t$. Using the properties of the modulus of continuity, we see that the function $h(t)/g(t) = h(t)/t$ is decreasing. Thus if D is a $\text{Lip}_{h,g}$ -extension domain, then D is also a Lip_g -extension domain, and by Corollary 2.2 there exists $c < \infty$ such that

$$\inf_{\gamma(x,y)} l(\gamma) = \epsilon_D(x,y) \geq c g(x,y) = c|x-y|.$$

So D is quasiconvex.

Notice that a $\text{Lip}_{h,g}$ -extension domain need not to be quasiconvex, see [L, Theorem 5.1].

Olli Martio introduced uniform domains in [M]. A domain D in \mathbb{R}^n is c -uniform if every $x, y \in D$ can be joined with a rectifiable curve γ in D such that

$$(2.2) \quad l(\gamma) \leq c|x-y|,$$

and

$$(2.3) \quad \text{dist}(\gamma(t), \partial D) \geq \frac{1}{c} \min(t, l(\gamma)-t).$$

A domain is called uniform, if it is c -uniform for some $c < \infty$. The snowflake or the Koch curve described in Mandelbrot [Ma, p.42] is an example of a uniform domain whose boundary is very irregular.

If the modulus of continuity h increases too fast near 0, then there is no $\text{Lip}_{h,g}$ -extension domain; see [L, Lemma 4.11]. As a matter of fact, we can prove the following theorem for the existence of the $\text{Lip}_{h,g}$ -extension domains.

Theorem 2.5. Let h and g be two moduli of continuity. Then the following conditions are equivalent:

(i) There are constants $K < \infty$ and $t_K > 0$ such that for every $0 < t \leq t_K$

$$\int_0^t \frac{h(s)}{s} ds \leq K g(t) .$$

(ii) All bounded uniform domains are $\text{Lip}_{h,g}$ -extension domains.

(iii) The unit ball in \mathbb{R}^n is a $\text{Lip}_{h,g}$ -extension domain.

(iv) There exists at least one $\text{Lip}_{h,g}$ -extension domain.

Proof. Suppose first that (i) holds. From the properties of the modulus of continuity h it follows that $h'(t) \leq h(t)/t$ and so $h(t) \leq K g(t)$ whenever $0 < t \leq t_K$. Let D be a c -uniform domain with the diameter d_D . Choose $x, y \in D$ and γ as in the definition for c -uniform domain. Since $h(t)/t$ is decreasing we obtain from the definition of h_D

$$\begin{aligned} h_D(x, y) &\leq \int_0^{l(\gamma)} \frac{h(\text{dist}(\gamma(s), \partial D))}{\text{dist}(\gamma(s), \partial D)} ds \leq \\ &\leq 2 \int_0^{\frac{l(\gamma)}{2}} \frac{h(s/c)}{s/c} ds \leq \\ &\leq 2c \int_0^{\frac{l(\gamma)}{2}} \frac{h(s)}{s} ds , \end{aligned}$$

because $c \geq 1$. If $l(\gamma)/2 \leq t_K$, then

$$h_D(x, y) \leq 2cKg(l(\gamma)/2) \leq 2cKg(c|x-y|) \leq 2c^2Kg(|x-y|) ,$$

and by Theorem 2.1 D is a $\text{Lip}_{h,g}$ -extension domain.

If $l(\gamma)/2 > t_K$, then

$$\begin{aligned} h(l(\gamma)) &\leq h(c|x-y|) \leq \operatorname{ch}(d_D) = \operatorname{ch}\left(\frac{d_D}{t_K} \cdot t_K\right) \leq \\ &\leq c \max\left(\frac{d_D}{t_K}, 1\right) h(t_K) \leq c \Delta K g(t_K) \leq c \Delta K g(l(\gamma)), \end{aligned}$$

where $A = \max(d_D/t_K, 1)$, and so $h_D \prec g$ in D :

$$\begin{aligned} 2c \int_0^{l(\gamma)/2} \frac{h(s)}{s} ds &= 2c \int_0^{t_K} \frac{h(s)}{s} ds + 2c \int_{t_K}^{l(\gamma)/2} \frac{h(s)}{s} ds \leq \\ &\leq 2cK g(t_K) + 2c h(l(\gamma)) \int_{t_K}^{l(\gamma)/2} \frac{1}{s} ds \leq \\ &\leq 2c \left(K g(l(\gamma)) + cAK g(l(\gamma)) \ln \frac{l(\gamma)}{2t_K} \right) \leq \\ &\leq 2cK \left(1 + cA \ln \frac{c|x-y|}{2t_K} \right) g(c|x-y|) \leq \\ &\leq 2c^2K \left(1 + cA \ln \frac{cd_D}{2t_K} \right) g(|x-y|). \end{aligned}$$

Thus D is a $\operatorname{Lip}_{h,g}$ -extension domain.

Next, we show that (iv) implies (i). Let D be a $\operatorname{Lip}_{h,g}$ -extension domain. Take a point $y_0 \in D$ and choose a point $x_0 \in \partial D$ such that the line segment $J(x_0, y_0) \subset D \cup \{x_0\}$. Let G be the complement of x_0 and $t_K := |x_0 - y_0|$. Let $0 < t \leq t_K$ and $0 < \varepsilon < t$. Choose points $x, y \in J(x_0, y_0)$ such that $|x - x_0| = \varepsilon$ and $|y - x_0| = t$. By Theorem 2.1

there exists a constant \bar{K} such that $h_D(x,y) \leq K g(x,y)$ and trivially $h_G(x,y) \leq h_D(x,y)$. So

$$\int_{\xi}^t \frac{h(s)}{s} ds = h_G(x,y) \leq h_D(x,y) \leq K g(x,y) = K g(t-\xi),$$

and (i) holds by letting $\xi \rightarrow 0$.

This completes the proof, since the fact that a unit ball is uniform and (iv) follows trivially from (iii).

Modifying the previous proof we have the same theorem for unbounded domains:

Theorem 2.6. Let h and g be two moduli of continuity. Then the following conditions are equivalent:

(i) There is a constant $K < \infty$ such that for every $t > 0$

$$\int_0^t \frac{h(s)}{s} ds \leq K g(t).$$

(ii) All uniform domains are $Lip_{n,g}$ -extension domains.

(iii) The complement of a point in R^n is a $Lip_{n,g}$ -extension domain.

By Theorem 2.5 and Theorem 2.6 one could think that $Lip_{n,\varepsilon}$ -extension domains are exactly uniform domains. But that is not the case even with Lip_n -extension domains. In [L, Lemma 4.26] and [GM2, Example 2.26(c)] there are examples of non-uniform Lip_n -extension domains.

For an other characterization for $Lip_{n,\varepsilon}$ -extension domains

based on the maximum derivative see [L, Theorem 7.3] and [GM1].

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STRESZCZENIE

Mówimy, że funkcja rzeczywista u określona w niepustym obszarze $D \subset \mathbb{R}^n$ należy do klasy globalnej Lipschitza $\text{Lip}_h(D)$, jeśli istnieje stała $M < \infty$, taka $u(x): |u(x) - u(y)| \leq M h(|x-y|)$ dla wszystkich $x, y \in D$, gdzie $h: (0; +\infty) \rightarrow \mathbb{R}$ jest funkcją rosnącą i wklęsłą (moduł ciągłości). Funkcja u należy do klasy lokalnej Lipschitza $\text{loc Lip}_h(D)$, jeśli istnieją stałe $b \in (0; 1)$, $M = m_b$ także, że $(*)$ ma miejsce dla każdego $x \in D$ i każdego y w kuli $B(x, b \text{ dist}(x, \partial D))$. W pracy bada się obszary, dla których obie klasy pokrywają się.

РЕЗЮМЕ

Вещественная функция и определенная в непустой области $D \subset \mathbb{R}^n$ принадлежит к глобальному классу Липшица $\text{Lip}_h(D)$, если существует постоянная $M < \infty$, такая, что $|u(x) - u(y)| \leq M h(|x-y|)$ для всех $x, y \in D$ где $h: (0; +\infty) \rightarrow \mathbb{R}$ возрастающая и вогнутая (модуль непрерывности). Функция принадлежит к локальному классу Липшица $\text{loc Lip}_h(D)$, если существуют постоянные $b \in (0; 1)$, $M = m_b$, такие, что $(*)$ имеет место для произвольного $x \in D$ и всех y в шаре $B(x, b \text{ dist}(x, \partial D))$. В этой работе были исследованы области, для которых эти классы совпадают.

