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Instytut Matematyki Uniwersytet Marii Curie-Sklodowskiej

W.MOZGAWA

Curvature and Torsion Tensors of Quasi-connection on Manifold with Singular Tensor

Tensory krzywizny i skręcenia quasi-koneksji na rozmaitości z tensorem osobliwym

Тонзоры кривизны и кручения квази-связности на многообразии с сингулярным тензором

Let $(FM, M, Gl(n), \omega)$ be a bundle of linear frames on M with a connection ω . It is well known that for any connection following structure equations hold:

$$d\Theta^{\gamma} = \Theta^{\alpha} \wedge \omega^{\gamma}_{\alpha} + \frac{1}{2} T^{\gamma}_{\alpha\beta} \Theta^{\alpha} \wedge \Theta^{\beta}$$

$$d\omega^{\lambda}_{\mu} = \omega^{\gamma}_{\mu} \wedge \omega^{\lambda}_{\gamma} + \frac{1}{2} R^{\gamma}_{\mu\alpha\beta} \Theta^{\alpha} \wedge \Theta^{\beta}$$
(1)

where ω_{α}^{γ} , Θ^{β} , α , β , $\gamma = 1, ..., n$ are the connection form and canonical form on FM, resp.

Let's consider $n + n^2$ vector fields E_{λ}^{s} , E_{α} on FM, dual to ω_{α}^{s} and Θ^{s} . Usually we call these vector fields fundamental vector fields and standard vector fields, resp. We have the following identities for these vector fields :

$$\Theta^{\beta}(E_{\alpha}) = \delta^{\beta}_{\alpha} \qquad \Theta^{\beta}(E^{\mu}_{\alpha}) = 0$$

$$\omega^{\rho}_{\sigma}(E_{\alpha}) = 0 \qquad \omega^{\rho}_{\sigma}(E^{\mu}_{\lambda}) = \delta^{\rho}_{\lambda}\delta^{\mu}_{\sigma}.$$
(2)

We can write the structure equations (1) in the dual form :

$$\begin{split} [E^{\mu}_{\lambda}, E^{\sigma}_{\rho}] &= \delta^{\mu}_{\rho} E^{\sigma}_{\lambda} - \delta^{\sigma}_{\lambda} E^{\mu}_{\rho} \quad , \qquad [E_{\alpha}, E^{\mu}_{\lambda}] = -\delta^{\mu}_{\alpha} E_{\lambda} \\ [E_{\alpha}, E_{\beta}] &= -T^{\gamma}_{\alpha\beta} E_{\gamma} - R^{\lambda}_{\mu\alpha\beta} E^{\mu}_{\lambda} \end{split}$$
(3)

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Yung - Chow Wong has considered the natural question what is the set of n vector fields E_{α} on FM which satisfies the equation:

$$[E_{\alpha}, E_{\lambda}^{\mu}] = -\delta_{\alpha}^{\mu} E_{\lambda}.$$

In this way he obtained a generalization of the linear connection viz. the so called quasi-connection. The standard vector fields E_{α} of a quasi-connection are given locally by

$$E_{\alpha} = x_{\alpha}^{j} \left(C_{j}^{i} \frac{\partial}{\partial x^{i}} - x_{\gamma}^{k} \Phi_{jk}^{i} \frac{\partial}{\partial x_{\gamma}^{i}} \right)$$

where C_{j}^{i} , Φ_{jk}^{i} are functions of x^{i} only and such that on $U \cap U' \neq \emptyset$ with coordinate systems $(U, x^{i}), (U', x^{i'})$ we have

$$A_j^{\mathfrak{a}'}C_{\mathfrak{a}'}^{\mathfrak{i}'}=C_j^{\mathfrak{a}}A_{\mathfrak{a}}^{\mathfrak{i}'}$$

$$\Phi^a_{jk}A^{i'}_a = C^a_j A^{i'}_{ak} + A^{a'}_j A^{b'}_k \Phi^i_{a'b'}$$

$$A_{a}^{i'} = \frac{\partial x^{i'}}{\partial z^{a}}, \qquad A_{jk}^{i'} = \frac{\partial^2 x^{i'}}{\partial z^j x^k}.$$

It is easy to see that, if the tensor C is non-singular on M, then

$$\Gamma^i_{jk} := C_j^{-1a} \Phi^i_{ak}$$

are components of a linear connection.

We assume that rank C = m < n throughout this paper. We also assume that the distribution in C is involutive (i.e. there exist functions λ_{kl}^i such that $C_{lk}^a C_{llle}^i = \lambda_{kl}^a C_{k}^i$, cf. [6]).

In [6] Y - Ch.Wonghas proved the following theorem :

If (C, Φ) is a quasi-connection on M, then for any tensors X, Y, Z of type (1,0), (0,1), (1,1), respectively, on M

$$\nabla_{l} X^{i} = C_{l}^{a} X^{i}_{|a} + X^{a} \Phi^{i}_{la}$$

$$\nabla_{l} Y_{j} = C_{l}^{a} Y_{j|a} - \Phi^{a}_{lj} Y_{a}$$

$$\nabla_{l} Z^{i}_{l} = C_{l}^{a} Z^{i}_{la} + Z^{a} \Phi^{i}_{la} - \Phi^{a}_{lj} Z^{i}_{a}$$
(4)

are components in (U, z^i) of tensors of type (1, 1), (0, 2), (1, 2) respectively on M. Moreover, the following equations hold :

$$\nabla_{l}(X^{i}Y_{j}) = (\nabla_{l}X^{i})Y_{j} + X^{i}\nabla_{l}Y_{j}$$

$$\nabla_{l}(X^{a}Y_{a}) = C_{l}^{b}(X^{a}Y_{a})_{|b}.$$
(5)

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Curvature and Torsion Tensors of Quasi-connection

We call the operator ∇ the covariant derivative with respect to quasi-connection on M.

Having considered the third structure equation (3) Y-Ch.Wong established the following

Theorem (cf. [6]) Let (C, Φ) be any quasi-connection on M. Assume that the tensor C is of constant rank m on M and its field of image m-planes is involutive, so that $C_{ik}^{a}C_{i||a}^{i} = \lambda_{kl}^{a}C_{a}^{i}$ in every coordinate system (U, x^{i}) . Then there exists on M a tensor S of type (1, 2) satisfying the equation:

$$S_{kl}^{h}C_{h}^{i} = (\Phi_{kl}^{h} - \lambda_{kl}^{h})C_{h}^{i}$$
(6)

in every (U, z^i) . Moreover, for any such tensor S

$$R^{i}_{jkl} = G^{a}_{[k} \Phi^{i}_{l]j|a} - \Phi^{a}_{[kj} \Phi^{i}_{l]a} - \Phi^{a}_{[kl]} \Phi^{i}_{aj} + S^{a}_{kl} \Phi^{i}_{aj}$$
(7)

are components in (U, z^i) of a tensor R of type (1, 3) on M.

However, this theorem is rather difficult for applications because the tensor S given in involved form is not unique. In this paper we give reasonable assumptions under which we are able to determine curvature and torsion tensor of quasi-connection. We also give the formulae of Levi-Cicita quasi-connection and some properties of above mentioned tensors.

We assume that C is a singular tensor of a quasi-connection (C, Φ) on M such that its Nijenhuis tensor

$$N(X,Y) = [CX,CY] - C[X,CY] - C[CX,Y] + C^{2}[X,Y]$$
(8)

is equal to zero. We hope that this assumption is reasonable because in the last time many structures with singular (1, 1) tensors were considered and the condition N(X, Y) = 0 often appears in these papers.

Theorem 1. If (C, Φ) is guasi-connection on M then

$$T_{jk}^{*} = \Phi_{jk}^{*} + C_{[j|k]}^{*} + F_{kl}^{*}$$
(9)

are components in (U, z') of a tensor T of type (1, 2) on M where

$$P \in \{P \in TM \otimes \Lambda^2 TM^{\bullet}; \text{ im } P = \ker C\}.$$

Proof. It is sufficient to consider the transformation law of $C^{\epsilon}_{[j|k]}$ and $\Phi^{\epsilon}_{[jk]}$ where the transformation law of $C^{\epsilon}_{(jk)}$ is

$$C^{a}_{[j]k]}A^{b}_{a} = -A^{i}_{x[k}C^{x}_{j} + A^{i}_{x[j]}C^{b}_{k} + C^{i}_{[a'|b']}A^{a}_{j}A^{b'}_{k}.$$

Theorem 2. If (C, Φ) is quasi-connection on M and the Nijenhuis tensor N of C is zero then the tensor T satisfies the identity (6)

$$T^{h}_{kl}C^{i}_{h} = (\Phi^{h}_{|kl|} - \lambda^{h}_{kl})C^{i}_{h}$$

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Proof. A local expressions of the Nijenhuis tensor N is

$$N_{kl}^{h} = C_{[k}^{a} C_{l]|a}^{h} - C_{[l|k]}^{a} C_{a}^{h} = 0 .$$
 (10)

Let's rewrite the formula (6) in the form

$$S_{kl}^{h}C_{h}^{i} = \Phi_{[kl]}^{h}C_{h}^{i} - \lambda_{kl}^{h}C_{h}^{i} = \Phi_{[kl]}^{h}C_{h}^{i} - C_{[k}^{a}C_{l]|_{\#}}^{i}.$$
 (11)

If we substitute (10) in (11) then

$$S^{h}_{kl}C^{i}_{h} = \Phi^{h}_{[kl]}C^{i}_{h} - C^{a}_{[l|k]}C^{i}_{a} = \Phi^{a}_{[kl]}C^{i}_{a} + C^{a}_{[k|l]}C^{i}_{a} = = (\Phi^{a}_{[kl]} + C^{a}_{[k|l]})C^{i}_{a} = (\Phi^{a}_{[kl]} + C^{a}_{[k|l]} + P^{a}_{kl})C^{i}_{a} .$$

so $T_{kl}^{\epsilon} = \Phi_{[kl]}^{\epsilon} + C_{[k|l]}^{\epsilon} + P_{kl}^{\epsilon}$ satisfies (6). We shall call the tensor T the torsion tensor of quasi-connection. Lemma 3. The torsion tensor T can be globally defined by

$$T(X,Y) = \nabla_X Y - \nabla_Y X - [X,CY] - [CX,Y] + C[X,Y] + P(X,Y).$$
(12)

Proof. It is sufficient to consider (4). Corollary 1. The torsion tensor is skew-symmetric:

$$T(X,Y) = -T(Y,X) \tag{13}$$

Corollary 2. If T is the torsion tensor of quasi-connection (C, Φ) on M then (C, Ψ) where $\Psi = \Phi - \frac{1}{2}T$ is a new quasi-connection on M without torsion.

Lemma 4. The curvature tensor R can be globally defined by

$$R_{XY}Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X,CY]} Z - -\nabla_{[CX,Y]} Z + \nabla_{C[X,Y]} Z + \nabla_{P(X,Y)} Z.$$
(15)

Proof. It is sufficient to express (15) in local coordinates. For an arbitrary smooth function f on M we define:

$$\delta_Z f = Z^j C_j^k f_{|k}$$
, $Z = Z^j \frac{\partial}{\partial z^j}$. (16)

Let's introduce an exterior derivative δ of 1-forms with respect to the singular tensor C (with the condition N = 0) by

$$(\delta\omega)(X,Y) = \delta_X \omega(Y) - \delta_Y \omega(X) +$$
$$-\omega \left([X,CY] + [CX,Y] - C[X,Y] + P(X,Y) \right). \tag{17}$$

Now we can state the following

Theorem 5. If (C, Φ) is guasi-connection on M then the following structure equations hold

$$\delta(dz^{i}) + \omega_{t}^{i} \wedge dz^{t} = \frac{1}{2}T_{jk}dx^{j} \wedge dz^{k}$$

$$\delta\omega_{j}^{i} + \omega_{t}^{i} \wedge \omega_{j}^{t} = \frac{1}{2}R_{jkm}^{i}dz^{k} \wedge dz^{m}$$
(18)

where $\omega_j^i = \Phi_{kj}^i dx^k$.

Proof is straightforward if one considers (18) and the definitions of T_{jk} and R_{ikm}^{i} .

Now we can say what does it mean that the quasi-connection is Riemannian.

Definition. The quasi-connection ∇ on M is said to be Riemannian with respect to scalar product g if

$$\delta_Z g(X,Y) = g(\nabla_Z X,Y) + g(X,\nabla_Z Y), \qquad T(X,Y) = 0.$$
(19)

Theorem 6. Let (M,g) be a Riemannian manifold. Then there exists a unique Riemannian guasi-connection for a given singular tensor C.

Proof. We do it in the same way as in the classical proof. By summing up the identities:

 $\delta_U g(V, W) = g(\nabla_U V, W) + g(V, \nabla_U W)$

$$\partial_V g(W,U) = g(V_V W,U) + g(W,V_V U)$$

$$-\delta_W g(U, Y) = -g(\nabla_W U, Y) - g(U, \nabla_W Y)$$

we obtain with the help of (13)

$$2g(\nabla_{V}U,W) = \delta_{U}g(V,W) + \delta_{V}g(W,U) - \delta_{W}g(U,V) - -g(T(U,V),W) - g([U,CV] + [CU,V] - C[U,V],W) + +g(T(W,U),V) + g([W,CU] + [CW,U] - C[W,U],V) + +g(T(W,V),U) + g([W,CV] + [CW,V] - C[W,V],U).$$
(20)

It means that $\nabla_V U$ is completely determined by g, T, C and the derivatives of g and C. In the local coordinates (U, z^i) this quasi-connection has the following form:

$$\begin{aligned} \dot{P}_{bl}^{i} &= \frac{1}{2} g^{il} \left(C_{l}^{a} g_{kl|a} + C_{k}^{a} g_{ll|a} - C_{l}^{a} g_{kl|a} + \\ &+ g_{al} T_{lk}^{a} + g_{al} C_{(k|l)}^{a} + g_{ak} T_{ll}^{a} + g_{ak} C_{(l|l)}^{a} + \\ &+ g_{al} T_{lk}^{a} + g_{al} C_{[k|l]}^{a} \right). \end{aligned}$$

$$(21)$$

It is necessary to check the transformation law of quasi-connection (C, Φ) given by (21) but the calculations are rather lengthy and are omitted here. If we put T = 0 we obtain the quasi-connection which is a generalization of Levi-Civita connection

$$\Phi_{kl}^{i} = \frac{1}{2}g^{il} \left(C_{l}^{a}g_{kl|a} + C_{k}^{a}g_{ll|a} - C_{l}^{a}g_{kl|a} + g_{al}C_{[k|l]}^{a} + g_{al}C_{[k|l]}^{a} + g_{al}C_{[k|l]}^{a} + g_{al}C_{[k|l]}^{a} \right).$$
(22)

Corollary 3. One can check directly that we have $\nabla g = 0$ for the above quasiconnection.

Theorem 7. For the curvature tensor of Riemannian manifold we have following identities:

a)
$$R_{XY}Z = -R_{YX}Z$$

b) $R_{XY}Z + R_{YZ}X + R_{ZX}Y = 0$
c) $g(R_{XY}Z, W) = -g(R_{XY}W, Z)$

- d) $g(R_{XY}Z,W) = g(R_{ZW}X,Y)$.

Proof.

a) is straightforward

b) is almost straightforward but one should use few times Jacobi identity and our condition N(X, Y) = 0

c) under our assumption N(X, Y) = 0 we have

$$\delta_{[X,CY]+[CX,Y]-C[X,Y]+P(X,Y)}g(W,Z) = (\delta_X \delta_Y - \delta_Y \delta_X)g(W,Z)$$
(24)

and now the proof is similar to the classical case.

d) it follows from a), b), and c).

Taking into account the parallel displacement by D i C o m i t e[1] we will give a geometric interpretation of the curvature tensor of quasi-connection. According to [1] the parallel displacement of a vector field X holds along an integral curve of a vector field C(Y) and is given by

$$\nabla_Y X = \left(\frac{dX^k}{dt} + Y^i \Phi^k_{ij} X^j\right) \frac{\partial}{\partial z^k} = 0$$
 (25)

We shall move infinitesimally a frame $A_j \frac{\partial}{\partial x^i}$ (such that $A_j^i(m_0) = \delta_j^i$) starting in the direction of the vector Y and then in the direction of the vector X, afterwards we shall subtract from this a quantity obtained by the parallel displacement of the frame $A_j^i \frac{\partial}{\partial x^i}$ at first in the direction X and then in the direction Y.

It is well known that in the case of linear connection we shall obtain an infinitesimal of second order that is just a curvature tensor, here we will obtain also a curvature tensor but with a "correction". Ourvature and Torsion Tensors of Quasi-connection

Let's now consider the equation

$$\nabla_X A_i^i = 0 \tag{26}$$

that is

$$\frac{dA_j^i}{dt} + \Phi_{kt}^i X^k A_j^t = 0$$
⁽²⁷⁾

hence

$$A_{j}(m_{0} + tX + h.o.t.) = \delta_{j}^{*} - t\Phi_{kj}^{*}(m_{0})X^{*}(m_{0}) + h.o.t.$$
(28)

where h.o.t. denotes the higher order terms. Now we shall move the frame $A_{j}^{i}(m_{0} + tX + h.o.t.)$ in the direction of the vector Y starting at the point $m_{0} + tX + h.o.t.$

$$\begin{aligned} A_{j}^{i}(m_{0} + tX + tY + h.o.t.) &= (\delta_{j}^{i} - t\Phi_{kj}^{i}(m_{0})X^{k}(m_{0}) + h.o.t.) - \\ -t\Phi_{kp}^{i}(m_{0} + tC(X) + h.o.t.)Y^{k}(m_{0} + tC(X) + h.o.t.) \\ &\left(\delta_{j}^{*} - t\Phi_{kj}^{p}(m_{0})X^{*}(m_{0}) + h.o.t.\right) + h.o.t. = . \end{aligned}$$
(29)
$$= \delta_{j}^{i} - t\left(\Phi_{kj}^{i}X^{k} + \Phi_{kj}^{i}Y^{k}\right)_{|m_{0}} - t^{2}\left(\Phi_{kj|s}^{i}C_{l}^{*}X^{l}Y^{k} + \\ + \Phi_{kj}^{i}\delta_{C}(X)Y^{k} - \Phi_{kp}^{i}\Phi_{kj}^{p}X^{s}Y^{k}\right)_{|m} + h.o.t. \end{aligned}$$

If we perform it in opposite order then we obtain

$$\hat{A}_{j}^{i}(m_{0} + tX + tY + h.o.t.) = \delta_{j}^{i} - t(\Phi_{kj}^{i}Y^{k} + \Phi_{kj}^{i}X^{k})_{|m_{0}} + t^{2}(\Phi_{kj}^{i}\delta_{C}(Y)X^{k} + \Phi_{kj|a}^{i}C_{l}^{a}Y^{l}X^{k} - \Phi_{kp}^{i}\Phi_{kj}^{p}X^{k}Y^{k})_{|m_{0}} + h.o.t.$$
(30)

After subtraction we obtain

$$A_{j}^{i} - \tilde{A}_{j}^{i} = t^{2} [R_{jkl}^{i} X^{l} Y^{k} + \Phi_{kj}^{i} ([CX, Y]^{k} + [X, CY]^{k} - C[X, Y]^{k} - P^{k} (X, Y)] + h.o.t.$$
(31)

Thus the term at t^2 is just the curvature tensor of quasi-connection and the "correction"

$$[CX,Y] + [X,CY] - C[X,Y] + P(X,Y]$$
(32)

which also appeared in (12), (15), and (17). The correction (32) has the following interpretation – it is a counterpart of the Poisson bracket for the vector fields X and Y with respect to the singular tensor C.

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STRESZCZENIE

Dia quasi-konekaji speiniającej pewne naturalne salożenia wysnaczono tensory skręcenia i krzywizny oraz podano ich wiazności. Podano także uogólnienie konekaji Levi-Civita.

PESIOME

Для квази-связности выполняющей некоторые естественные условия получено тензоры кручения и кривизны вместе с тем представлено их свойства. Получено обобщение связности Леви-Чивита.