#### ANNALES

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Invariant Connections of Higher Order on Homogeneous Spaces Koneksje niezmiennicze wyższych rzędów na przestrzeniach jednorodnych Инвариантные связности высших порядков на однородных многообразиях

The paper contains a construction of higher order connections on a given principal fibre bundle over a homogeneous differentiable manifold. We work with an Ehresmann groupoid which is associated with this bundle. We consider its r-th prolongation and we construct a certain connection of order q. We prove that the obtained connection is invariant with respect to the group action convenably prolonged. For properties of this connection cf. [7].

#### I. PRELIMINARIES AND NOTATIONS

Let  $(H,B,G,\pi)$  be a principal fibre bundle over a manifold B. Denote by  $\Phi$  the groupoid which is associated with

# Witold Mozgawa, Andrzej Szybiak

(H,B,G, $\pi$ ). Thus elements of  $\Phi$  are G-isomorphisms of fibres over B. Thus  $\Phi$  is a smooth manifold which is provided with the two projections, a and b, viz. if  $\Theta \in \Phi$ sends a fibre through  $\pi^{-1}(m)$  to  $\pi^{-1}(m')$  then we set  $a \Theta = m$  and  $b \Theta = m'$ . It is easy to see that if we are given any two points h and k then there exists exactly one element  $\Theta_{h,k} \in \Phi$  such that  $\Theta_{hk}$  sends the fibre through h to the fibre through k, in such a way that for each  $g \in G$ it holds  $\theta_{hg,kg} = \Theta_{h,k}$ . The element which is reciprocal to a given  $\Theta \in \Phi$  will be denoted by  $\sigma \Theta$ . Evidently we have  $\sigma \Theta_{h,k} = \Theta_{kh}$  and  $a\sigma \Theta = b\Theta$ . We define a mapping  $\psi: \Phi^{\times}H \longrightarrow H$  by  $\psi(\Theta,h) = \Theta(h)$ . If  $x \in B$  then we denote the identity mapping of  $\pi^{-1}(x)$  by  $\tilde{x}$ .

If we fix any  $m_0 \in B$  then  $\{\Theta \in \Phi \mid a\Theta = m_0\}$  is a fibre bundle which is isomorphic with (H,B,G, $\pi$ ). Analogously  $\{\Theta \in \Phi \mid b\Theta = m_0\}$  is some bundle which is called a co-bundle of (H,B,G, $\pi$ ).

Thus  $\{\Theta \in \varphi \mid a\Theta = b\Theta = m_0\}$  is a group and it is isomorphic to G.

We shall use standard notations of jet calculus [1 - 5], but if necessary we introduce and explain some new ones. Thus  $\alpha$  and  $\beta$  denote, respectively, the source and the target projections.

 $J^{\mathbf{r}}(\mathbf{B}, \boldsymbol{\varphi})$  denotes the set of non-holonomic jets of order r from the manifold B to the manifold  $\boldsymbol{\varphi}$ . Thus  $J^{\mathbf{r}}(\mathbf{B}, \boldsymbol{\varphi})$ has a natural structure of a groupoid over  $J^{\mathbf{r}}(\mathbf{B}, \mathbf{B})$ , [2]. a<sup>r</sup> and b<sup>r</sup> are the prolonged mappings a and, respectively, b. It maps  $J^{\mathbf{r}}(\mathbf{B}, \boldsymbol{\varphi})$  onto  $J^{\mathbf{r}}(\mathbf{B}, \mathbf{B})$ . If we fix some m then  $\{\mathbf{X} \in J^{\mathbf{r}}(\mathbf{B}, \boldsymbol{\varphi}) \mid \alpha(\mathbf{a}^{\mathbf{r}}(\mathbf{X})) = \mathbf{m}\}$  is a principal fibre bundle over

B. [9]. x being any point of B,  $\rho_x$  denotes the mapping which sends all points of B to x and we put  $\rho_x^r := j_x^r \rho_x$ . Then we introduce the space  $\widetilde{Q}^r(x)$  to be  $\widetilde{J}^r(B, \Phi)$  restricted to

 $\left\{ \mathbf{x} \mid \alpha(\mathbf{x}) = \mathbf{x}, \quad \beta(\mathbf{x}) = \widetilde{\mathbf{x}}, \quad \mathbf{a}^{\mathbf{r}}(\mathbf{x}) = \boldsymbol{\rho}_{\mathbf{x}}^{\mathbf{r}}, \quad \mathbf{b}^{\mathbf{r}}(\mathbf{X}) = \mathbf{j}_{\mathbf{x}}^{\mathbf{r}} \mathbf{1}_{\mathbf{B}} \right\}.$  $\widetilde{Q^{r}}(x)$  is a fibre over x of a certain bundle  $\widetilde{Q^{r}}$  over B cf. [1]. [4]. Qr admits global crossections. [1]. [4]. because its standard fibre is homeomorphic with a Cartesian space of a convenable dimension. A cross-section  $B \longrightarrow Q^{T}$  is a connection of order r on the principal bundle H and an element X of this cross-section over a point  $x \in B$  will be called an element of the connection of order r. Let us consider such a cross-section  $\Xi$  and a point  $x \in B$  and put  $X = \Xi(x)$ . We are going to define a connection form for . To begin with we have to know what is  $X^{-1}$ ?  $X^{-1}$  is a non-holonomic jet  $\tilde{\mathbf{x}}$ , where  $\tilde{\boldsymbol{\sigma}}^{\mathbf{r}}$  is a non-holonomic prolongation of the mapping 6. Denote by  $\widetilde{\psi}^{\mathbf{r}}$  a prolongation up to order r of the natural action of the groupoid  $\phi$  on the bundle H. Thus  $\tilde{\psi}^r$  is an action of  $\tilde{J}^r(H, \phi)$  on  $\tilde{J}^r(H, H)$ . We consider some  $z \in H$  and we put  $\pi(z) = x$ . Thus  $\pi^r j_{\pi}^r 1_H \in J^r(H,B)$ . Then we denote

# $\mathbf{X}^{-1} \nabla \mathbf{j}_{\mathbf{z}}^{\mathbf{r}} \mathbf{1}_{\mathbf{H}} := \widetilde{\boldsymbol{\Psi}}^{\mathbf{r}} ((\mathbf{X}^{-1}) (\boldsymbol{\pi}^{\mathbf{r}} \mathbf{j}_{\mathbf{z}}^{\mathbf{r}} \mathbf{1}_{\mathbf{H}}), \ \mathbf{j}_{\mathbf{z}}^{\mathbf{r}} \mathbf{1}_{\mathbf{H}})$

The result is an element of  $J^{r}(H, \pi^{-1}(x))$ , [1],[4]. Then we define  $T^{r}H$  as a dual space to  $J^{r}(H,R)_{0}$ , i.e.  $T^{r}H =$ =  $(J^{r}(H,R)_{0})^{r}$ . The element  $X^{-1} \vee j_{z}^{r} 1_{H}$  gives rise to a unique linear mapping  $(X^{-1} \vee j_{z}^{r} 1_{H})^{r}$  of the vector space  $J^{r}(\pi^{-1}(x),R)_{0}$  into  $J^{r}(H,R)_{0}$  and a unique linear mapping

# Witold Mozgawa, Andrzej Szybiak

 $(X^{-1} \vee j_z^r 1_{H})_*$  of  $T^r H$  into  $T^r (\pi^{-1}(x))$ . Given any  $z \in H$  we define by [z] an identification of the fibre through z with the group G such that e corresponds to z. Analogously we prolong [z] to mapping

$$[z]_{*}^{r}: \widetilde{T}_{z}^{r} \pi^{-1}(x) \longrightarrow \widetilde{T}_{e}^{r}G$$
.

Then the connection from (1) of order r of Z is defined by

(1) 
$$\omega(\mathbf{v}) = ([\mathbf{z}]^{\mathbf{r}} \cdot \mathbf{X}^{-1} \mathbf{v} \mathbf{j}_{\mathbf{z}}^{\mathbf{r}} \mathbf{1}_{\mathrm{H}})_{*}(\mathbf{v})$$

for  $v \in T_g^r H$ . The basic references for this section are [1], [4].

#### II. BASIC CONSTRUCTIONS

From now we assume that there is given a Lie group and a transitive regular left action

# τ : K×B → B / (g,m) → T(g,m)

q being a positive integer we define  $\tilde{\tau}^{q}(-,-)$  as a q-lift of  $\tau$ , which acts on the manifold of non-holonomic frames  $H_q$  over B. Then we proceed by induction. Let X be a non--holonomic q-frame on B, i.e. a regular element of  $J_0^q(\mathbb{R}^d, B)$ where  $d = \dim B$ . We put  $X_1 = j_1^q X$ , where  $J_1^q$  denotes a projection of jets of order q into jets of order 1. Thus  $X_1$  is a frame of order 1 and there exists a regular local mapping  $f: \mathbb{R}^d \longrightarrow B$  such that  $j_{X|0}^1f(x) = X_1$ . Then we put

$$\widetilde{\tau}^{1}(g, X_{1}) := j_{x|0}^{1} \tau(g, f(x))$$

Let us assume that  $\tilde{\tau}^{q-1}$  is defined. Then  $X = j_0^1 \xi$ ,  $\xi$ being some cross, section in  $\tilde{J}^{q-1}(\mathbb{R}^d, \mathbb{B})$ . We put

$$\widetilde{\tau}^{q}(g,X) := j_{x|0}^{1} \widetilde{\tau}^{q-1}(g, \xi(x))$$

PROPOSITION 1.  $\tilde{\tau}^q$  defines an associative left action, i.e.

$$\tilde{\tau}^{q}(k, \tilde{\tau}^{q}(1, -)) = \tilde{\tau}^{q}(k1, -)$$

By definition, a non-holonomic q-coframe on B is a regular q-jet whichs source is in M and its target is at O in  $\mathbb{R}^d$ . Let  $\mathbb{H}_q^{\pi}$  be the bundle of q-coframes on B. Then K acts on  $\mathbb{H}_q^{\pi}$  by the following manner:

If  $Y \in H_q^*$ ,  $a \in K$ , we put  $Y_1 = j_1^Q Y$ , so that  $Y = j_m^1 f$ . Then we put

$$\tau^{1}(a, \mathbf{X}_{1}) := j^{1}_{\tau(a, m)} f(\tau(a, -))$$

Then we pass to higher order by a standard inductive proceeding.

PROPOSITION 2. There holds the following formula for the just described action of K on  $H_0^{\#}$ 

$$\tau^{q}(b, \tau^{q}(a, Y)) = \tau^{q}(ab, Y)$$

Thus  $\tilde{\tau}^{q}$  is an associative right action.

Let  $X_0$  be a fixed q-frame at some point  $m_0 \in B$ . We lead into considerations the following set of q-frames on B

$$W_q = \{ \tilde{\tau}^q(k, X_o) | k \in K \}$$

We define on  $W_q$  a projection  $\pi_q$  onto B by the following formula

$$\mathfrak{R}_{q}(\tilde{\mathcal{T}}^{q}(k, \mathbb{X}_{0})) = \mathcal{T}(k, \mathbb{M}_{0})$$

We denote by  $\widetilde{L}_q^d$  the structure of Lie group on a set  $J^q(\mathbb{R}^d, \mathbb{R}^d)$ , restricted to regular jets and we denote by

$$\mathbf{K}_{\mathbf{m}} := \left\{ \mathbf{g} \in \mathbf{K} \mid \mathcal{T}(\mathbf{g}, \mathbf{m}) = \mathbf{m} \right\}$$

the stability group of T .

PROPOSITION 3. For any m & B a mapping

$$\chi_{\tilde{x}_0} : K_m \longrightarrow \tilde{L}_q^d / k \longmapsto X_0^{-1} \cdot \tilde{\tau}^q(k, \tilde{x}_0)$$

is a homomorphism of Lie groups.

Proof. Given any q-frame X then there exists a unique q-coframe  $X^{-1}$  which may be viewed as follows: we consider  $J_1^{q}X = X_1$  which is a regular 1-jet, i.e.  $X_1 = j_0^{-1}f$ so that  $X_1^{-1} = j_{f(0)}^{-1}f^{-1}$  the (q-1)-coframes being defined we take a cross-section such that  $X = j_0^{-1}\xi$ ,  $\xi : \mathbb{R}^d \to W_{q-1}$ and we put  $X^{-1} := j_X^{-1}|_{f(0)}(\xi(x))^{-1}$ .

In order to prove that  $\chi_{X_0}$  is in fact a homeomorphism we use Proposition 1 and we have

$$\chi_{X_0}(kl) = X_0^{-1}(\widetilde{\tau}^{q}(kl, X_0)) = X_0^{-1}(\widetilde{\tau}^{q}(k, X_0 X_0^{-1} \widetilde{\tau}^{q}(l, X_0)) =$$
$$= X_0^{-1}(\widetilde{\tau}^{q}(k, X_0) X_0^{-1} \widetilde{\tau}^{q}(l, X_0) = \chi_{X_0}(k) \chi_{X_0}(l)$$

We introduce the following notations:  $\widetilde{G}_q(X)$  resp.  $\widetilde{G}_q(X)$ , is the image of  $K_m$  by  $\chi_X$ , resp.  $\chi_X$ , X and X being any two elements of the bundle  $W_q$  at m and at p respectively.

PROPOSITION 4. There exists an isomorphism  $\widetilde{G}_q(\mathbf{X})$  ----- $\widetilde{G}_p(\mathbf{Y})$  such that following diagram is commutative

Proof. Let  $g \in K$  be any element which sends X to Y. Thus  $K_p$  and  $K_m$  are  $Adj_g$  - related. Let us define a mapping

$$G_{q}: \widetilde{G}_{q}(\mathbf{I}) \longrightarrow \widetilde{G}_{q}(\mathbf{I})$$

(2)

$$\mathbf{X}^{-1} \widetilde{\tau}^{\mathbf{q}}(\mathbf{k}, \mathbf{X}) \longleftrightarrow \widetilde{\tau}^{\mathbf{q}}(\mathbf{g}^{-1}, \mathbf{X}^{-1}) \widetilde{\tau}^{\mathbf{q}}(\mathbf{g}\mathbf{k}\mathbf{g}^{-1}, \widetilde{\tau}^{\mathbf{q}}(\mathbf{g}, \mathbf{X}))$$

Keeping in mind that  $T^{q}(g, X) = X$  we obtain

$$\chi_{Y}(gkg^{-1}) = Y^{-1} \tilde{\tau}^{Q}(gkg^{-1}, I) =$$
  
=  $\tilde{\tau}^{Q}(g^{-1}, X^{-1}) \tilde{\tau}^{Q}(gkg^{-1}, \tilde{\tau}^{Q}(g, I)) = \sum_{g} (\chi_{X}(k))$ 

Since we may view  $S_g$  to be mapping which sends any  $\chi_{\chi}(k)$  to  $\chi_{\chi}(Adj_k)$  then there holds

$$S_{\rm g} = \chi_{\rm X} = \chi_{\rm Y} \circ {\rm Adj}_{\rm g}$$

Evidently 5g is an isomorphism.

The above results imply the following

THEOREM 5. Given any fixed frame  $X_0 \in H_q$  then there exists a unique frame bundle  $W_q$  over B with the structure group  $\tilde{G}_q$ , the image by  $\chi_{X_0}$  of the isotropy group  $K_{H_0}$ .  $X_q$  is the projection.

#### III. ELEMENTS OF INVARIANT CONNECTIONS

Let us fix any point  $m \in B$ . Denote by K and respectively, by K<sub>m</sub> the Lie algebras of K and of K<sub>m</sub>. Let  $D_m$  be any complementary space with respect to  $K_m$  in K. We choose a linear basis  $[\bullet_1, \dots, \bullet_d]$  in  $D_m$ . In some neighbourhood U of 0 in R<sup>d</sup> there is defined a mapping

$$[t^1,...,t^d] \mapsto \exp(\sum_{\alpha=1}^d t^\alpha \bullet_{\alpha}) =: g(t)$$

Let us consider the mapping

(3) 
$$t \mapsto \mathcal{T}(g(t), m)$$

This mapping is a diffeomorphism of U to some neighbourhood V of m.

Let

$$I: V \longrightarrow \mathbb{R}^d$$

be reciprocal to the mapping (3). We have w(m) = 0.

X being a frame in the fibre  $\pi_q^{-1}(m)$  we consider the mapping  $\Theta$  defined by

$$\Theta(t,m,X) := \widetilde{\tau}^{q}(g(t),X)$$

Thus  $\theta(t,m,-)$  maps the fibre  $\pi_q^{-1}(m)$  to the fibre  $\pi^{-1}(\tau(g(t),m))$ . We remark that if t = w(p) for some  $p \in V$ , then we have

$$\Theta(t,m,-)$$
 :  $\pi_q^{-1}(m) \longrightarrow \pi_q^{-1}(p)$ 

THEOREM 6.  $\Theta(t,m,-)$  is a fibre morphism of  $\pi_q^{-1}(m)$ to  $\pi_q^{-1}(\tau(g(t),m))$ .

Proof. We have to show that  $\Theta(t,m,-)$  commutes with the cononical action of  $\widetilde{G}_q$ , that means, the following diagram is commutative:

$$\begin{array}{c|c} \pi_{q}^{-1}(\mathbf{m}) & \underline{\theta(t, \mathbf{m}, -)} & \pi_{q}^{-1}(\mathbf{p}) \\ \chi_{z}(\mathbf{h}) & & & \\ \pi_{q}^{-1}(\mathbf{m}) & \underline{\theta(t, \mathbf{m}, -)} & \pi_{q}^{-1}(\mathbf{p}) \end{array}$$

for any  $K_m$  and by any choice of  $Z \in \pi_q^{-1}(m)$ . We see that Adj<sub>g(t)</sub>h  $\in K_p$  and  $W \in \pi_q^{-1}(p)$  is a map of Z by  $\tilde{\tau}^q(g(t), -)$ . Then the group  $\tilde{G}_q$  acts on the fibre  $\pi_q^{-1}(m)$  by the following rule

$$T: \widetilde{G}_{q} \times \pi_{q}^{-1}(m) \longrightarrow \pi_{q}^{-1}(m)$$
$$(\chi_{\tau}(h), X) \longrightarrow \widetilde{\tau}^{q}(kh, \widetilde{\tau}^{q}(k^{-1}, X))$$

Here  $k \in K$  is such that  $X = \tilde{\tau}^{Q}(k,Z)$ . Thus T defines a right action. Consider the mapping  $\pi_{q}^{-1}(m) \longrightarrow \pi_{q}^{-1}(p)$  given by

we have

(4)  $\Theta(t,m,\tilde{\tau}^{q}(kh,Z)) = \tilde{\tau}^{q}(g(t),\tilde{\tau}^{q}(kh,Z)) = \tilde{\tau}^{q}(g(t)kh,Z)$ On the other hand we have

 $\Theta(t,m,X) = \Theta(t,m,\tilde{\tau}^{q}(k,Z)) = \tilde{\tau}^{q}(g(t),\tilde{\tau}^{q}(k,Z))$ 

In view of formula (2) we have

$$\chi_{W}(h) = \mathcal{F}^{q}((g(t))^{-1}, z^{-1}) \mathcal{F}^{q}(g(t)h(g(t))^{-1}, \mathcal{F}^{q}(g(t), z)))$$

By consequence

 $T(\chi_{W}(h), \Theta(t, m, X)) =$   $= \tilde{\tau}^{Q}(g(t), \tilde{\tau}^{Q}(k, Z)) \tilde{\tau}^{Q}(g(t), Z^{-1}) \tilde{\tau}^{Q}(g(t)h(g(t))^{-1}, \tilde{\tau}^{Q}(g(t), Z)) =$   $= \tilde{\tau}^{Q}(g(t)kh(g(t))^{-1}, \tilde{\tau}^{Q}(g(t), Z)) = \tilde{\tau}^{Q}(g(t)kh, Z)$ 

If we compare this result with (4) then we finish the proof.

Let us denote by  $\phi_q$  the groupoid associated with  $W_q$ . Thus each  $\theta(t,m,-)$  is an element of  $\phi_q$ . Then we define an action of the group K on these elements of  $\phi_q$ . We put

 $k \neq \Theta(t,m,-) := \Theta(t, \tau(k,m),-)$ 

If  $X \in \pi_q^{-1}(\tau(k,m))$  then we have  $k \neq \Theta(t,m,X) = \Theta(t,\tau(k,m),X) = \tilde{\tau}^q(g(t),X) \in \pi_q^{-1}(\tau(g(t)k,m)).$ 

PROPOSITION 7. If  $\tau(k,m) = \tau(1,m)$  then we have

$$\mathbf{k} \neq \boldsymbol{\theta}(\mathbf{t}, \mathbf{m}, -) = \mathbf{l} \neq \boldsymbol{\theta}(\mathbf{t}, \mathbf{m}, -)$$

IV. BUNDLES OF INVARIANT ELEMENTS OF THE CONNECTION

Let us define a cross-section

$$C : B \longrightarrow J^{\mathbf{r}}(B, \Phi_q)$$

by  $C_p := j_{s|p}^r k * \Theta(w(\tau(k^{-1},s)),m,-)$  where k is such that

 $\tau(k,m) = p$ . In view of Proposition 7, C<sub>p</sub> does not depend on the choice of k. Then we see that C is a cross-section in the bundle of elements of the connection, that means:

1° 
$$\alpha(C_p) = p$$
  
2°  $\beta(C_p) = \tilde{p}$   
3°  $a^r(C_p) = \rho^r_x$   
4°  $b^r(C_p) = J^r_p I_B$ 

Remark that

$$C_{m} = j_{s|m}^{r} \Theta(w(s), m, -)$$

Then we put by definition

$$\widetilde{\tau}^{r}C_{m} := j_{t/m}^{r}k * \Theta(w(t), m, -)$$

and

$$C_{m} \widetilde{\tau}_{k-1}^{r} := j_{t|\tau_{k}(m)}^{r} \Theta(w(\tau(k^{-1},t)),m,-)$$

The following identities follow easily by definitions

$$\tau(\mathbf{k},\mathbf{m}) = \widetilde{\tau}_{\mathbf{k}}^{\mathbf{r}} \widetilde{\tau}_{\mathbf{m}} \widetilde{\tau}_{\mathbf{k}}^{\mathbf{r}}$$

and

(5) 
$$C_{\tau(k,m)}^{-1} = \widetilde{\tau}_{k}^{r} C_{m}^{-1} \widetilde{\tau}_{k}^{r}$$

Let us turn to the constructions in the preceeding chapter. The construction of the mapping w does depend on a choice of the complementary space  $D_m$  but it does not depend on a choice of the linear basis in  $D_m$ . Thus  $C_m$  and, by consequence, the cross-section  $p \mapsto C_p$  depends only on the choice of  $D_m$ . We have seen that each  $C_p$  is the element of the connection in the sense indicated in our preliminaries. Let us recollect the notations.

If  $Z \in W_q$  then [Z] is a diffeomorphism of the fibre through Z to the group  $G_q$  and [Z](Z) = e (neutral element in the group  $G_q$ ). Then we prolong [Z] to a mapping  $[Z]_{*}^r$ of  $T_Z^r W_q = (J_Z^r (W_q, R)_q)^*$  onto  $T_0^r G_q$ . Then we have to prolong  $\psi: \Phi \times W_q \longrightarrow W_q$  to  $\tilde{\psi}^r$  which acts on  $J^r (W_q, \Phi_q) \times J^r (W_q, W_q)$  and maps it to  $J^r (W_q, W_q)$ . Then the value of the form of our connection  $\omega_q^r$  on the element  $y \in T^r W_q$  at the point Z is, by definition

(6) 
$$\omega_{\mathbf{q}}^{\mathbf{r}}(\mathbf{y}) = \left\{ [\mathbf{Z}]^{\mathbf{r}} \cdot \widetilde{\boldsymbol{\psi}}^{\mathbf{r}} (\mathbf{C}_{\mathbf{m}}^{-1} \mathbf{j}_{\mathbf{Z}}^{\mathbf{r}} \boldsymbol{\pi}_{\mathbf{q}}, \mathbf{j}_{\mathbf{Z}}^{\mathbf{r}} \mathbf{j}_{\mathbf{q}}^{\mathbf{r}}) \right\}_{*} (\mathbf{y}), \quad \boldsymbol{\pi}_{\mathbf{q}} (\mathbf{Z}) = \mathbf{m}$$

The compositions inside the parantheses are to be understood as a non-holonomic jet composition. The group K acts on  $\widetilde{T}^{T}W_{q}$  by means of a non-holonomic lifting of  $\tau$ . This lift will be denoted by  $\widetilde{\tau}^{T}$ .

A connection is invariant under the action of K iff its form satisfies

$$\omega_q^r(\tilde{\tau}^r(k,y)) = \omega_q^r(y)$$

for each keK and each  $\mathbf{y} \in \mathbf{T}^{\mathbf{T}} \mathbf{W}_{\mathbf{q}}$ .

THEOREM 8. The connection defined above by C is invariant under K.

Proof. In view of (6) we have

 $\omega_{\mathbf{q}}^{\mathbf{r}}(\widetilde{\tau}^{\mathbf{r}}(\mathbf{k},\mathbf{y})) = = \left\{ \left[ \widetilde{\tau}^{\mathbf{q}}(\mathbf{k},\mathbf{z}) \right]^{\mathbf{r}} \widetilde{\psi}^{\mathbf{r}}(C_{\mathcal{T}(\mathbf{k},\mathbf{m})}^{-1} \mathbf{j}_{\widetilde{\tau}^{\mathbf{q}}(\mathbf{k},\mathbf{z})}^{\mathbf{r}} \pi_{\mathbf{q}}, \mathbf{j}_{\widetilde{\tau}^{\mathbf{q}}(\mathbf{k},\mathbf{z})}^{\mathbf{r}} \mathbf{1}_{\mathbf{W}_{\mathbf{q}}} \right\}_{\mathbf{x}} (\widetilde{\tau}^{\mathbf{r}}(\mathbf{k},\mathbf{y}))$ We make use of (5). Thus we have

(7) 
$$\omega_{0}^{r}(\tilde{\tau}^{r}(k,y)) =$$

 $= \left\{ \left[ \tilde{\tau}^{q}(\mathbf{k}, \mathbb{Z}) \right]^{r} \tilde{\psi}^{r} (\tilde{\tau}_{\mathbf{k}}^{r} c_{\mathbf{m}}^{-1} \tilde{\tau}_{\mathbf{k}}^{r} j_{\tilde{\tau}^{q}(\mathbf{k}, \mathbb{Z})}^{r} \pi_{q}, j_{\tilde{\tau}^{q}(\mathbf{k}, \mathbb{Z})}^{r} \eta_{q} \right) \right\}_{*} (\tilde{\tau}^{r}(\mathbf{k}, \mathbf{y}))$ First we notice that

$$\widetilde{\tau}_{k-1}^{\mathbf{r}} \mathbf{j}_{\widetilde{\tau}^{q}(k,Z)}^{\mathbf{r}} \mathbf{\pi}_{q} = (\mathbf{j}_{Z}^{\mathbf{r}} \mathbf{\pi}_{q}) \widetilde{\tau}_{k-1}^{\mathbf{r}}$$

and

$$\mathbf{j}_{\widetilde{\tau}^{q}(\mathbf{k},\mathbf{Z})}^{\mathbf{r}} \mathbf{W}_{q} = (\mathbf{j}_{\mathbf{Z}}^{\mathbf{r}} \mathbf{W}_{q}) \widetilde{\tau}_{\mathbf{k}}^{\mathbf{r}}$$

Consider the mapping  $([Z]^{\mathbf{r}} \tilde{\tau}^{\mathbf{r}}_{-1})$ , which is a linear mapping from  $\tilde{T}^{\mathbf{r}}_{\tilde{\tau}^{\mathbf{q}}(\mathbf{k},Z)} W_{\mathbf{q}}$  into  $\tilde{T}^{\mathbf{r}}_{\mathbf{e}} \tilde{G}_{\mathbf{q}}^{\mathbf{k}}$ . We have evident equality

$$([Z]^{\mathbf{r}} \widetilde{\tau}_{\mathbf{k}}^{\mathbf{r}})_{*} = [\widetilde{\tau}(\mathbf{k}, Z)]^{\mathbf{r}}_{*}$$

We substitute these above equalities to (7) and we obtain

 $\omega^{r}(\tilde{\tau}^{r}(k,y)) =$ 

 $= \left\{ \begin{bmatrix} Z \end{bmatrix}^{r} \widetilde{\tau}_{k}^{r} \widetilde{\tau}_{k}^{r} \widetilde{\tau}_{k}^{r} \widetilde{\tau}_{k}^{r} \widetilde{\tau}_{m}^{-1} (j_{Z}^{r} \pi_{q}) \widetilde{\tau}_{k}^{r} \widetilde{\tau}_{k}^{-1} (j_{Z}^{r} \eta_{q}) \widetilde{\tau}_{k}^{r} \widetilde{\tau}_{k}^{-1} \right\}_{*} (\widetilde{\tau}_{k}^{r} (k, y)) =$   $= \left\{ \begin{bmatrix} Z \end{bmatrix}^{r} \widetilde{\tau}_{k}^{r} \widetilde{\tau}_{k}^{r} \widetilde{\psi} (c_{m}^{-1} j_{Z}^{r} \pi_{q}, j_{Z}^{r} \eta_{q}) \right\}_{*} ((\widetilde{\tau}_{k}^{r})_{*} (\widetilde{\tau}_{k}^{r})_{*} (\widetilde{\tau}_{k}^{r})_{*} (y)) =$   $= \left\{ \begin{bmatrix} Z \end{bmatrix}^{r} \widetilde{\psi}^{r} (c_{m}^{-1} j_{Z}^{r} \pi_{q}, j_{Z}^{r} \eta_{q}) \right\}_{*} (y) = \omega_{q}^{r} (y)$ 

 $\tilde{\tau}_{\mathbf{k}}^{\mathbf{r}}$  is  $\tilde{\tau}^{\mathbf{r}}(\mathbf{k},-)$  for abbreviation of notations. The first of authors of this paper has proved in [7] the following theorem.

THEOREM 9. If q = r = 1 then above invariant connection  $\omega_1^1$  is flat.

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#### STRESZCZENIE

Rozważamy rozmaitość B o wymiarze d, na której działa lewostronnie grupa Liego K. Działanie to przedłużamy (na ogół nie holonomicznie) do działania grupy K na rozmaitości żetów  $J_0^{q}(\mathbb{R}^d,\mathbb{B})$ . Z przedłużeniem tym wiąże się konstrukcja pewnej wiązki reperów q-tego rzędu nad B, niezmienniczej względem K. W tej wiązce konstruujemy niezmienniczą koneksję r-tego rzędu oraz formę tej koneksji.

#### Резрие

В данной работе рассматривается многообразие В размерности d, на котором действует с лева группа Ли К. Это действие продолжаем неголономически к действию группы на многообразии струи  $J_0^{\alpha}(\mathbb{R}^d, B)$ инвариантного относительно к действию группы К. Строится инвариантная связность порядка q и форма этой связности в раслоённом пространстве реперов порядка q над В, являющемся определенной редукцией пучка всех q-реперов. Построено также форму такой связности. Дальнейшие ее свойства изучаются в последующей работе [8]

