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A Note on Extremal Properties for Certain Family of Convex Mappings

Własności ekstremalne pewnej rodziny odwzorowań wypukłych

Экстремальные качества некоторого семейства выпуклых отображений

1. Introduction

Let S^c denote the class of functions f(z) regular and univalent in the unit disk $K_1(K_r = \{z: |z| < r\})$, with f(0) = 0, f'(0) = 1 and such that the image domain $f(K_1)$ under every f belonging to S^c is convex.

It is well-known that $K_{1/2} \subset f(K_1)$ for any $f \in S^c$. However, if $f(z) \neq z(1-\varepsilon z)^{-1}$, $|\varepsilon| = 1$, there exists R, 1/2 < R < 1 such that

Thus, the studying of the class $S^c(R)$, 1/2 < R < 1, of all functions $f \in S^c$ which satisfy the condition (1.1) seems to be interesting.

In the paper [2] J. Krzyż investigated the class C(M), M > 1 of all functions f(z) belonging to S^c and satisfying

$$(1.2) f(K_1) \subset K_M.$$

He determined precise bounds for

(1.3)
$$|f(z)|; (1-|z|^2)|f'(z)|; |a_2| = \frac{1}{2}|f''(0)|(f \in C(M)),$$

using the Hadamard's variational method.

Let $\delta(M)$ denote the so-called Koebe constant for the class C(M), and let C(R, M); $\delta(M) < R < 1 < M < \infty$ denote the subclass of C(M)of all functions f(z) satisfying

Adopting the method used in [2] we can also find the estimates of the functionals (1.3) in the class C(R, M).

Hence, we shall also obtain the bounds of the functionals (1.3) in the class $S^{c}(R) = \bigcup_{M>1} C(R, M)$.

This problem was investigated in my Ph. D. thesis submitted to the Faculty of Mathematics, Physics and Chemistry of Maria Curie-Skłodowska University in Lublin.

2. Main result

Let us put

$$(2.1) G(z) = \frac{4}{(2+a)^{\alpha}} \frac{[\alpha(1+z)+2\lambda(z)]^{\alpha}}{[1+z+\lambda(z)]^2} \frac{z}{(1-z)^{\alpha}},$$

where $\lambda(z) = [1 + (a^2 - 2)z + z^2]^{1/2}, \quad 0 < a < 2,$

(2.2)
$$F(z) = \int_0^z \frac{G(\xi)}{\xi} d\xi.$$

The function G maps the unit disk K_1 onto a starshaped domain being the union of the disk K_o , where

(2.3)
$$\varrho = 4 [(2-a)^{2-a}(2+a)^{2+a}]^{-1/2}$$

and the angle $\{w: |\operatorname{Arg} w| < a^{\pi/2}\}$, (see [4]).

Examining the behaviour of the boundary of $G(K_1)$ under the transformation (2.2) we find that $F(K_1)$ is a convex circular domain D_F symmetric w.r.t. the real axis whose boundary consists of an arc situated on the boundary of the disk K_R , where

(2.4)
$$R = \int_{-1}^{0} \frac{G(t)}{t} dt$$

and two half a lines (or segments) starting from the end points of that arc and tangent to the boundary of K_R .

After some calculations we get the following formula:

(2.5)
$$R = R(a) = 16a \int_{a}^{1} t^{a} \frac{(2+a)t^{2}+2-a}{[(2+a)^{2}t^{2}-(2-a)^{2}]^{2}} dt$$

with
$$q = \sqrt{\frac{2-a}{2+a}}$$
.

Clearly, the function F(z) defined by (2.2) belongs to $S^{c}(R)$ with R given by (2.5).

Moreover, the function F(z) has interesting extremal properties. We now give one of them.

Theorem 1. Suppose that $f \in S^c(R)$, 1/2 < R < 1. Then $-F(-|z|) \leq |f(z)| \leq F(|z|)$

$$\mathbf{r} (-|\mathbf{v}|) \leq |\mathbf{j}(\mathbf{v})| \leq \mathbf{r} (|\mathbf{v}|).$$

3. Proof of Theorem 1

Let U = U(R, M), $\delta(M) < R < 1 < M$, denote the family of closed convex domains D containing the disk K_R included in the closed circle $\overline{K_M}$ and such that the inner conformal radius r(0, D) = 1.

Obviously, for any domain $D \in U$ there exists $f \in C(R, M)$ such that $\overline{f(K_1)} = D$.

Let $g(w, \eta; D)$ denote the classical Green's function of the domain D with the pole η . By the compactness of the family U, there exist two extremal domains $D_0, d_0 \in U$, such that

(3.1)
$$\sup_{D \in U} g(0, \eta; D) = g(0, \eta; D_0),$$

(3.2)
$$\inf_{D \in U} g(0, \eta; D) = g(0, \eta; d_0) \text{ provided } |\eta| < R.$$

As pointed out by J. Krzyż [2] the problem of determining the extremum of the functional $|f(re^{it})|$ in the class C(R, M) is equivalent to that of finding the domains D_0 , $d_0 \in U$ which are satisfying (3.1); (3.2) resp.

In other words, if $\overline{\Phi(K_1)} = D_0$, then

$$|\eta|\,=\sup_{f, heta}|f(re^{i heta})|\,=\sup_{ heta}|\varPhi(re^{i heta})|$$

and if $\varphi(K_1) = d_0$, then

$$|\eta| = \inf_{f, heta} |f(re^{i heta})| = \inf_{ heta} |arphi(re^{i heta})|, \; |\eta| < R$$
 .

Henceforth, we shall find the domains D_0 , d_0 , using the Hadamard's variational formulas [3] p. 46.

(3.3)
$$\delta g(w,\eta;D) = \frac{1}{2\pi} \int_{L} \frac{\partial}{\partial n_{\xi}} g(\xi,w;D) \frac{\partial}{\partial n_{\xi}} g(\xi,\eta;D) \,\delta n(s) \, ds \,,$$

(3.4)
$$\delta_{\gamma}(w; D) = \frac{1}{2\pi} \int_{L} \left[\frac{\partial}{\partial n_{\xi}} g(\xi, w, D) \right]^{2} \delta n(s) ds,$$

where $\gamma(w; D)$ denotes the Robin's constant, L is the boundary of D and $\partial/\partial n_s$ is the derivative in the direction of the inward normal n(s) = tp(s). The above given formulas are valid when the boundary L of the convex domain D consists of a finite system of analytic arcs, whereas the function p(s) is bounded and continuous except perhaps, a finite number of points. If the normal vector n(s) = tp(s) is directed outside D then p(s) > 0; otherwise p(s) < 0.

Taking into consideration the relation between the function h(w) which conformally maps $D \setminus L(D \in U)$, onto the disk K_1 with h(0) = 0, and the Green's function of D we bring the formulas (3.3) and (3.4) to a form more convenient for our purposes (see [2]):

(3.5)
$$\delta g(0, \eta; D) = \frac{1}{2\pi} \int_{L} |h'(w)|^2 X(w) \, \delta n(s) \, ds,$$

(3.6)
$$\delta_{\gamma}(0; D) = \frac{1}{2\pi} \int_{L} |h'(w)|^2 \, \delta n(s) \, ds,$$

where

 $X(w) = (1 - |h(w)|^2) |h(w) - h(\eta)|^{-2}.$

We also shall use the following

Lemma 1 [2]. Suppose that the boundary L of the domain D is a Jordan curve and let the points A, B, C divide L into three arcs which do not degenerate to points. Then we can always choose two arcs: L_1 , L_2 that for any arcs l_1 , l_2 .

 $l_1 \subset L_1, \ l_2 \subset L_2$ the inequality

$$\max_{w \in I_2} X(w) < \min_{w \in I_2} X(w)$$

holds.

In order to determine the domain D_0 we introduce the family $U_n \subset U$ of closed convex polygonal domains D_n with at most *n* vertices. Clearly $\bigcup_{n=1}^{\infty} U_n$ is dense in *U*. By the compactness of the family U_n there exists an extremal domain \bar{D}_n such that

 $g(0, \eta; \tilde{D}_n) = \sup g(0, \eta; D_n); D_n \in U_n.$

The same technique as in [2] leads to the following characterisation of the extremal polygonal domain D_n .

Lemma 2. The polygon \overline{D}_n has exactly n vertices. At most one vertex of \overline{D}_n situated inside K_M joins two sides neither tangent to the boundary of K_R .

Let now the sequence $\{D_n\}$, $D_n \in U_n$, be convergent in the sense of kernel convergence to the domain D_0 having the extremal property (3.1) in U. Then

$$\lim g(0, \eta; D_n) = g(0, \eta; D_0).$$

On the other hand, for each $n \ge 3$

$$g(0, \eta; D_n) \leqslant g(0, \eta; D_n) \leqslant g(0, \eta; D_0).$$

This implies that there exists a subsequence $\{\vec{D}_{n_k}\}$ convergent to $\vec{D}_0 \in U$ and such that

$$g(0, \eta; D_0) = g(0, \eta; D_0).$$

Let Γ_0 denote the boundary of D_0 . According to Lemma 2, Γ_0 consists of the segments and the circular arcs situated on the boundary of K_M or K_R .

We shall use here the method of eliminating those domains which have not the extremal property (3.2). The idea of eliminating is following: Consider a domain $D \in U$ and let D_t , 0 < t < T, be the domain formed from D by certain deformation of the boundary ∂D where $D_t \rightarrow D$ as $t \rightarrow 0$. If $D_t \in U$ and $g(0, \eta; D_t) > g(0, \eta; D)$ then the domain D evidently cannot have the extremal property (3.2).

We now prove that Γ_0 cannot contain more than two straight line segments. Suppose contrary to this that Γ_0 contains three segments. Hence $\Gamma_0 = \bigcup_{k=1}^{3} \Gamma_k$ and each Γ_k contains one segment. In view of Lemma 1 we can chose two segments l_1, l_2 such that the condition (3.7) is satisfied. We deform now the boundary of the domain D using the deformation described in [2] by shifting l_1 outside whereas l_2 is turned inside D, so that the domain D_i obtained from D after deformation should belong to the family U. On the arc l_1 we have $\delta n(s) > 0$, whereas $\delta n(s) < 0$ on l_2 and $\delta n(s) = 0$ on the remaining part of the boundary. From the formula (3.6) we get

$$\gamma^{-0} = \gamma(0; D_t) - \gamma(0; D) = rac{1}{2\pi} \int\limits_{l_1+l_2} |h'(w)|^2 \, \delta n(s) \, ds + o(t) \, ds,$$

 $\delta n(s) = tp(s).$

Dividing both sides of the latter equality by t and making $t \rightarrow 0$, we obtain

(3.8)
$$\int_{l_1} |h'(w)|^2 p(s) ds = \int_{l_2} |h'(w)|^2 [-p(s)] ds.$$

From (3.7) and (3.8) we have:

$$\int_{I_1} |h'(w)|^2 X(w) \, \delta n(s) \, ds > \int_{I_2} |h'(w)|^2 X(w) [-\delta n(s)] \, ds \, ,$$

which means that $\delta g(0, \eta; D) > 0$ and also

$$\Delta g \, = \, g(0 \, , \, \eta \, ; \, D_t) \, - \, g(0 \, , \, \eta \, ; \, D) > 0 \; \; {
m for} \; \; 0 < t < T \, .$$

Using the same reasoning as above and the method of deformation of the convex domain described in [2] we find that Γ_0 is composed of two stright line segments and two arcs situated on δK_R and ∂K_M , resp.

The domain d_0 which minimizes the Green's function can be determined by an analogous argument (cf. [2]). It appears that $d_0 = \tilde{D}_0$ and in both cases the extremal domain is the same irrespective of the choice of the number η . Thus we have the characterisation of the extremal domain \tilde{D}_0 apart from rotations about w = 0. It is convenient to have the domain \tilde{D}_0 symmetric w.r.t. the real axis.

Remark. The solution of the problems (3.1); (3.2) can be extended on the limiting case $M = \infty$. By the above remark the proof of Theorem 1 is complete.

4. Conclusions

Suppose that $f \in C(R, M)$, and $\eta = f(z)$, $D = f(K_1)$. Then $r(\eta; D) = (1 - |z|^2) |f'(z)|$. Let us put $\gamma(\eta; D) = \log r(\eta; D)$. In view of (3.4) we obtain the following expression for the variation of the Robin's constant of D:

(4.1)
$$\delta\gamma(\eta; D) = \frac{1}{2\pi} \int_{L} |\varphi'(w)|^2 X^2(w) \, \delta n(s) \, ds.$$

The formula (4.1) is valid if L consists of a finite system of analytic arcs. The function $X^2(w)$ has similar property of monotonity like X(w). By analogous argumentation as in sect. 3 one can prove

Theorem 2. If $f \in S_R^*$, $D_F = F(K_1)$ (F is defined by (2.2)) then

$$(1 - |z|^2) |f'(z)| \leq r(|f(z)|; D_F)$$

and for $|f(z)| \leq R$

$$r(-|f(z)|; D_F) \leqslant (1-|z|^2) |f'(z)|.$$

(cf. [2]).

Let $F(z) = z + A_2 z^2 + ...$ be the function given by (2.2). Since F is extremal in the problem $\max |f(re^{it})|$, $f \in S^c(R)$, $|A_2|$ is also extremal in the problem $\sup |a_2|$, $a_2 = \frac{1}{2} |f''(0)|$, $f \in S^c(R)$ (see [1], p. 8).

Thus we have

Theorem 3. If $f(z) = z + a_2 z^2 + \dots \epsilon S^c(R)$ then

$$|a_2| \leqslant \left(\!rac{a}{2}\!
ight)^{\!\!2}$$

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From (2.5) we have $R(1) = \frac{4}{9} + \frac{16}{27} \ln 2 = 0.855...$ If R > R(1) then R corresponds to a with 0 < a < 1. Hence, the right inequality of theorem 1 as well as (2.1), (2.2) give

Theorem 4. Suppose that R > R(1), $f \in S^{c}(R)$. Then

$$|f(z)|\leqslant R\left(\cos a\,rac{\pi}{2}
ight)^{-1},\,\,z\,\epsilon\,K_{1}.$$

We recall that a, R are connected by (2.5).

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STRESZCZENIE

Niech S^c oznacza klasę funkcji regularnych i jednolistnych w kole jednostkowym K_1 ($K_r = \{z \in \mathbb{C} : |z| < r\}$) i takich że dla każdoj funkcji $f \in S^c$ f(0) = f'(0) - 1 = 0, oraz $f(K_1)$ jest obszarem wypukłym płaszczyzny zespolonej \mathbb{C} .

Oznaczmy przez $S^c(R)$ podklasą klasy S^c funkcji f spełniających warunek

$$K_R \subset f(K_1), \quad \delta(M) < R < 1.$$

W pracy wyznaczono ekstremum funkcjonałów:

$$|f(z)|, (1-|z|^2)|f'(z)|, |a_2| = \frac{1}{2}|f''(0)|, f \in S^c(R)$$

(Twierdzenia: 1, 2, 3).

Rozważane ekstrema realizuje funkcja określona wzorem (2.2).

Ponadto wykazano, że jeśli $f \in S^c(R)$ i $R > \frac{4}{9} + \frac{16}{27} \ln 2$, to $|f(z)| < M(R), z \in K_1$ (Twierdzenie 4).

РЕЗЮМЕ

Пусть S^c обозначает класс равномерных и однолистных функций в единичном круге K_1 ($K_r = \{z \in \mathbb{C} : |z| < r\}$) а таких же для каждой функции $f \in S^c f(0) = f'(0) - 1 = 0, f(K_1)$ является выпуклым пространством комплексной плоскости C. Обозначим через $S^c(R)$ подкласс S^c функции f выполняя условия.

$$K_R \subset f(K_1), \ \delta(M) < R < 1.$$

В работе онределено экстремум функционалов:

$$|f(z)|, (1-|z|^2)|f'(z)|, |a_2| = \frac{1}{2}|f''(0)|, f \in S^c(R)$$

(теорема: 1, 2, 3)

Обсуждаемые экстремумы реализует функция представлена формулой (2.2). Показано, что если $f \in S^c(R)$ и $R > \frac{4}{9} + \frac{16}{27} \ln 2$ тогда f(z)| $< M(R), \ z \in K_1$ (Теорема 4).