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Instytut Matematyki, Uniwersytet Marii Curic-Skłodowskiej, Lublin

ZBIGNIEW ŚWIĘTOCHOWSKI

On Second Order Cauchy's Problem in a Hilbert Space with Applications to the Mixed Problems for Hyperbolic Equations, II

O zadaniu Cauchy'ego drugiego rzędu w przestrzeni Hilberta z zastosowaniem do zadań mieszanych dla równań hiperbolicznych, II

О задаче Коши второго порядка в гильбертовом пространстве с приложением к смешанным задачам для уравнений гиперболического типа, Il

The purpose of this paper is to give some applications of the results of Theorems 1 and 2 of the previous paper [6].

I. Let Ω be a bounded domain in \mathbb{R}^n , and let S be the boundary of Ω . We shall use the notation of [6] and the following ones:

- $D(\Omega)$ = the space of all complex-valued tested functions on Ω equipped with the usual topology,
- $(D)'\Omega$ = the conjugate space of $D(\Omega)$, i.e. the space of distributions in the sense of L. Schwartz on Ω ,
- $L^2(\Omega)$ = the Hilbert space of classes of complex-valued measurable and square-integrable functions over Ω with the usual scalar product $((u, v)) = \int_{\Omega} u(x)\overline{v(x)} dx$ and the norm $||u|| = ((u, u))^{1/2}$,
- $H^k(\Omega) = ext{ the Hilbert space of elements of } L^2(\Omega) ext{ having the distributional derivatives of order } \leqslant k$, square-integrable over Ω , with the scalar product $((u, v))_k = \sum_{|a| \leqslant k} ((D^a u, D^a v))$ and the norm $||u||_k = ((u, u))_k^{1/2}$.
- $H_0^k(\Omega) =$ the completion of $D(\Omega)$ in the norm of $H^k(\Omega)$,
- $\langle f, u \rangle$ = the value of $f \in D'(\Omega)$ at the point $u \in D(\Omega)$,
- $B^k(\Omega)$ = the set of all functions on Ω such that their partial derivatives of order $\leq k$ exist and are continuous and bounded.

II. A mixed problem with the boundary condition of the Dirichlet type.

Consider a hyperbolic equation of second order

(1)
$$\frac{\partial^2 u}{\partial t^2} + \sum_{i=1}^n a_i(t, x) \frac{\partial^2 u}{\partial x_i \partial t} - \sum_{i,k=1}^n a_{ik}(t, x) \frac{\partial^2 u}{\partial x_i \partial x_k} = 0,$$

where the coefficients are real-valued functions belonging to $B^2((0, T) \times \Omega)$. We assume that $\sum_{i,k=1}^n a_{ik}(t, x) \xi_i \xi k \ge d \sum_{i=1}^n \xi_i^2$ and $a_{ij}(t, x) = a_{ji}(t, x)$ for all $(t, x) \epsilon(0, T) \times \Omega$ and $(\xi_1, \ldots, \xi_n) \epsilon R^n$.

Our problem is to obtain a solution u(t, x) of (1) on $(0, T) \times \Omega$, $u(t, \cdot) \in H_0^-$ for every $t \in (0, T)$, satisfying

(2)
$$\begin{cases} u(0, x) = u_0(x) \\ \frac{\partial u}{\partial t}(0, x) = u_1(x) \end{cases}$$

 $u(t, x) = 0 \text{ for } (t, x) \in \langle 0, T \rangle \times S,$

for any given initial data $u_0(x)$, $u_1(x)$.

The derivatives in (1) in t are taken in the sense of the norm in $H_0^$ while in x_1, \ldots, x_n in the distributional sense. The second condition of (2) means that $u(t, \cdot) \in H_0^1(\Omega)$ for every $t \in \langle 0, T \rangle$.

The existence and the uniqueness of the solution of (1)-(2) under some assumption on $u_0(x)$, $u_1(x)$ will follow from Theorem 1 of [6]. In order to apply this theorem we set:

$$H = L^2(\Omega), \; H^+ = H^1_0(\Omega), \; H^+_t = H^1_0(\Omega)$$

with the scalar product and the norm defined by the formulae

$$egin{aligned} &((u\,,\,v))_t^+\,=\,\int\limits_{\Omega}\,u\,(x)\,\overline{v\,(x)}\,dx+\int\limits_{\Omega}\,\sum\limits_{i,k=1}^n a_{ik}(t\,,\,x)rac{|\partial\,u\,(x)|}{\partial x_i}\,rac{\partial\,v\,(x)}{\partial x_k}\,,\ &\|u\|_t^+\,=ig((u\,,\,u))_t^+ig)^{1/2}. \end{aligned}$$

By the definition of the operator $\Lambda_0(t)$ ([6], Lemma 5°) we have: $\int D(\Lambda(t)) = \int u dt H^+$, $\sup \int [(u - u)]^+ \int u dt H^+$, $||u|| \le 1 \le \infty$

(3)
$$\begin{cases} D(\Lambda_0(t)) = \{u \in H_t : \sup \{|((u, v))_t| : v \in H_t, \|v\| \leq 1\} < \infty\} \\ ((\Lambda_0(t)u, v)) = ((u, v))_t^+. \end{cases}$$

Now we explain the sense of (3) in the present case. Let $v \in D(\Omega)$ We have:

$$egin{aligned} &\langle \Lambda_0(t) \, u \, , \overline{v}
angle &= ig((u \, , v))_t^+ \, = \, \int\limits_\Omega u \, (x) \, \overline{v(x)} \, dx + \, \int\limits_\Omega \sum\limits_{i,k=1}^n a_{ik}(t \, , x) \, rac{\partial u \, (x)}{\partial x_i} \, rac{\partial v \, (x)}{\partial x_k} \, dx \ &= \Big\langle u - \sum\limits_{k=1}^n rac{\partial}{\partial x_k} \Big(\sum\limits_{i=1}^n a_{ik}(t \, , x) rac{\partial u}{\partial x_i} \Big) , \, \overline{v} \Big
angle. \end{aligned}$$

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Hence the conditions:

$$\begin{cases} u \in D(\Lambda_0(t)) \\ \left((\Lambda_0(t) u, v) \right) = (u, v) \right)_t^+, v \in H_0^1(\Omega) \end{cases}$$

are equivalent to the following ones

$$\left[\sum_{k=1}^{n} \frac{\partial}{\partial x_{k}} \left(\sum_{i=1}^{n} a_{ik}(t, x) \frac{\partial u(x)}{\partial x_{i}}\right)\right] \epsilon L^{2}(\Omega),$$
$$\Lambda_{0}(t)u = u - \sum_{k=1}^{n} \frac{\partial}{\partial x_{k}} \left(\sum_{i=1}^{n} a_{ik}(t, x) \frac{\partial u}{\partial x_{i}}\right)$$

in the sense of $D'(\Omega)$ for every $t \in \langle 0, T \rangle$.

From the equality $((\Lambda_0(t)u, v))_t^- = ((u, v))$ for $u \in D(\Lambda_0(t))$, $v \in H^+$, and from the inequality $|((u, v))| \leq ||u||_t^+ ||v||_t^-$ for $u \in H^+$, $v \in H$ it follows that $\Lambda_0(t)$ is a continuous operator, mapping $D(\Lambda_0(t))$ into H_t^- , and since $D(\Lambda_0(t))$ is a dense subset in H_t^+ , $\Lambda(t)$ = the closure of $\Lambda_0(t)$ in H_t^- is an element from $L(H_0^+, H_0^-)$, satisfying

$$\Lambda(t) u = u - \sum_{k=1}^{n} \frac{\partial}{\partial x_k} \left(\sum_{i=1}^{n} a_{ik}(t, x) \frac{\partial u}{\partial x_i} \right)$$

in the sense of $D'(\Omega)$. Write (1) in an equivalent form

(4)
$$\frac{d^2 u}{dt^2} + \left(\sum_{i=1}^n a_i(t, x) \frac{\partial}{\partial x_i}\right) \frac{du}{dt} - \sum_{i,k=1}^n a_{ik}(t, x) \frac{\partial^2 u}{\partial x_i \partial x_k} = 0$$

and put:

$$B(t)u = \left(\sum_{i=1}^{n} a_{i}(t, x) \frac{\partial}{\partial x_{i}}\right)u$$
$$S(t)u = -\sum_{i,k=1}^{n} a_{ik}(t, x) \frac{\partial^{2} u}{\partial x_{i} \partial x_{k}} + \sum_{i,k=1}^{n} \left(\frac{\partial}{\partial x_{k}}(Q_{ik}(t, x) \frac{\partial u}{\partial x_{i}}\right) - u.$$

Setting S(t) = P(t) - 1, we see P(t) is the first order differential operator. Writing (4) in the form

(5)
$$\frac{d^2u}{dt^2} + \left(A(t) + S(t)\right)u + B(t)\frac{du}{dt} = 0$$

We shall prove that the hypotheses (1.1) - (1.3) of Theorem 1 of paper [6] are fulfilled.

Ad (1.2). Let $u \in D(\Omega)$, $v \in H^+$. We have

$$ig \|ig(B(t)u\,,v)ig)ig| = ig| \int\limits_{\Omega} \sum\limits_{i=1}^n a_i(t\,,x) \, rac{\partial u}{\partial x_i} \, ar v dx ig| \leqslant \sum\limits_{i=1}^n \Big(\int\limits_{\Omega} a_i^2(t\,,x) \, \Big| rac{\partial u}{\partial x_i} \,\Big|^2 dx \Big)^{1/2} imes \ imes \Big(\int\limits_{\Omega} |v|^2 dx \Big)^{1/2} \leqslant c_1 \, \|u\|_0^+ \, \|v\|\,,$$

and

$$\left\|\left(\left(B\left(t
ight)u\,,\,v
ight)
ight)
ight|\,=\,\left|\,-\int\limits_{\Omega}\,\sum\limits_{i=1}^{n}\,rac{\partial}{\partial x_{i}}\left(a_{i}(t\,,\,x)\,\overline{v}
ight)udx\,
ight|\leqslant c_{2}\left\|u
ight\|\left\|v
ight\|_{0}^{+}.$$

Since

$$\|B(t) u\|_{0}^{-} = \sup \{|((B(t) u, v))| : v \in H^{+}, \|v\|_{0}^{+} \leq 1\},$$

thus for $u \in D(\Omega)$ we obtain

$$\|B(t)u\|_0^- \leq c_2 \|u\|.$$

From the density of $D(\Omega)$ in $H = L^2(\Omega)$, after extension by continuity we come to conclusion that $B(t) \epsilon L(H, H_0^-)$.

Ad (1.3). For every $u \in D(\Omega)$ we have

$$\begin{split} \left(\left(B\left(t\right)u\,,\,u\right)\right) &=\, -\int\limits_{\Omega} \sum_{i=1}^{n} \frac{\partial}{\partial X_{i}} \left(a_{i}(t\,,\,x)\,\bar{u}\right) u dx \,=\, -\int\limits_{\Omega} \sum_{i=1}^{n} \frac{\partial a_{i}(t\,,\,x)}{\partial x_{i}} \,|u|^{2} dx \,+\, \\ &- \int\limits_{\Omega} \sum_{i=1}^{n} a_{i}(t\,,\,x) \,\frac{\partial \bar{u}}{\partial x_{i}} \, u dx \,=\, -\int\limits_{\Omega} \sum_{i=1}^{n} \frac{\partial a_{i}(t\,,\,x)}{\partial x_{i}} \,|u|^{2} dx \,-\, \left(\left(u\,,\,B\left(t\right)u\right)\right). \end{split}$$

Thus

$$2\operatorname{Re}\bigl(\bigl(B(t)u,\,u\bigr)\bigr) = -\int\limits_{\Omega} \sum_{i=1}^{n} \frac{\partial a_i(t,\,x)}{\partial x_i} \,|u|^2 dx$$

and

$$\operatorname{Re}((B(t)u, u)) \leqslant c_3 ||u||^2.$$

Let $u \in H^+$. From the density of $D(\Omega)$ in H_0^+ it follows that there exists a sequence $u_n \in D(\Omega)$ such that $||u_n - u||_0^+ \to 0$. Of course also $||u_n - u|| \to 0$. By the inequality $|((B(t)u, v))| \leq c_1 ||u||_0^+ ||v||$ we see $B(t) \in L(H_0^+, H)$, hence $||B(t)u_n - B(t)u|| \to 0$. Finally, the passage to the limit when $n \to \infty$ in the inequality $|\operatorname{Re}((B(t)u_n, u_n))| \leq c_3 ||u_n||^2$ gives us the required one:

$$|\operatorname{Re}((B(t) u | u))| \leq c_3 ||u||^2$$
 for every $u \in H^+$ and $t \in \langle 0, T \rangle$.

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Ad (1.1). We can write

$$P(t)u = \sum_{i=1}^{n} c_i(t, x) \frac{\partial u}{\partial x_i},$$

where the coefficients $c_i(t, x)$ forms the combination of the derivatives of $a_{ik}(t, x)$. Thus we see $S(t) \in L(H_0^+, H)$.

The weakly continuously differentiability of the functions $t \rightarrow S(t)$ and $t \rightarrow B(t)$ follows from the forms of the operators S(t) and B(t) and from the properties of the coefficients $a_i(t, x)$ and $a_{ik}(t, x)$.

Hence all hypotheses of Theorem 1 are fulfilled. Moreover, bearing in mind Remark of [6] we see that the solution of problem (1)-(2) has the property:

$$u(t, \cdot) \epsilon C^0(\langle 0, T
angle; H^1(\Omega)) \cap C^1(\langle 0, T
angle; L^2(\Omega)) \cap C^2(\langle 0, T
angle; H^-_0).$$

Remark 1. Note, that H_0^- one can regard as the antiadjoint space of H^+ (cf. [2], p. 45). In our case when $H^+ = H_0^1(\Omega)$, the corresponding antiadjoint space is denoted by $H^{-1}(\Omega)$ (cf. [5]).

Applying Theorem 1 of [6] we have just proved the following

Theorem A. For given initial data $\{u_0(x), u_1(x)\} \in H_0^1(\Omega) \times L^2(\Omega)$ there exists one and only one solution u(t, x) of (1) - (2) such that

 $u(t,\,\cdot)\,\epsilon\,C_0\bigl(\langle 0\,,\,T\rangle\,;\,\,H^1_0(\varOmega)\bigr)\cap C^1\bigl(\langle 0\,,\,T\rangle\,;\,L^2(\varOmega)\bigr)\cap C^2\bigl(\langle 0\,,\,T\rangle\,;\,H^{-1}(\varOmega)\bigr)\,.$

Remark 2. Theorem 1 can be applied to more general equation, namely to the following one:

$$\begin{array}{l} (1^{\circ}) \qquad \frac{\partial^2 u}{\partial t^2} + \sum_{i=1}^n a_i(t,x) \, \frac{\partial^2 u}{\partial x_i \partial t} - \sum_{i,k=1}^n a_{ik}(t,x) \, \frac{\partial^2 u}{\partial x_i \partial x_k} + b(t,x) \, \frac{\partial u}{\partial t} + \\ \\ \qquad + \sum_{i=1}^n c_i(t,x) \, \frac{\partial u}{\partial x_i} + c(t,x) \, u \, = \, 0 \, . \end{array}$$

Putting

$$S_1(t)u = S(t)u + \sum_{i=1}^n c_i(t, x) \frac{\partial u}{\partial x_i} + c(t, x)u,$$
$$B_1(t)u = B(t)u + b(t, x)u,$$

one can easy check the conditions (1.1) - (1.3) of Theorem 1.

III. A mixed problem with the boundary condition of the transversal type.

In this section we consider again a mixed problem for hyperbolic equations of second order. The domain Ω and the equation are the same as they were in Section II. But we require now S to be sufficiently smooth, more precisely, Ω is an interior domain of the compact surface S of class C^{∞} in \mathbb{R}^n .

Our problem is to obtain u(t, x); $u(t, \cdot) \in H^1(\Omega)$ for $t \in \langle 0, T \rangle$, a solution of the equation

(i)
$$\frac{\partial^2 u}{\partial t^2} + \sum_{i=1}^n a_i(t, x) \frac{\partial^2 u}{\partial x_i \partial t} - \sum_{i,k=1}^n a_{ik}(t, x) \frac{\partial^2 u}{\partial x_i \partial x_k} = 0$$

and for given initial data $\{u_0(x), u_1(x)\}$ satisfying

(ii)
$$\begin{cases} u(0, x) = u_0(x) \\ \frac{\partial u}{\partial t}(0, x) = u_1(x) \end{cases}$$

and

$$(\text{iii}) \qquad \sum_{i,k=1} a_{i,k}(t,x) \frac{\partial u}{\partial x_i} \eta_k = -a(t,x) u, \text{ for } (t,x) \epsilon \langle 0\,,\,T\rangle \times S\,,$$

where a(t, x) is given real-valued, continuous, non-negative function on $\langle 0, T \rangle \times S$ and $\{\eta_k\}_1^n$ denotes the normal exterior vector with respect to surface S.

The derivatives in (i) in t are taken in the sense of the norm in $L^2(\Omega)$ whereas in x_1, \ldots, x_n in the distributional one.

In order to prove the existence and the uniqueness of the solution of (i)-(iii) we shall apply Theorem 2 of [6].

To do this we need the following assumptions:

a)
$$\sum_{i=1}^n a_i(t,x)\eta_i(x) = 0 ext{ for } (t,x)\epsilon\langle 0,T
angle imes S,$$

b)
$$\sum_{i,k=1}^{n} a_{ik}(0,x) \frac{\partial u_0}{\partial x_i} \eta_k(x) + a(0,x) u_0 = 0 \text{ for } x \in S.$$

Set: $H = L^2(\Omega)$, $H^+ = H^1(\Omega)$, $H_l^+ = H^1(\Omega)$ with the scalar product and the norm defined by formulae:

$$egin{aligned} &((u\,,v))_{l}^{+} = \int\limits_{\Omega} u\,(x)\overline{v\,(x)}\,dx + \int\limits_{\Omega} \sum\limits_{i,k=1}^{n} a_{ik}(t\,,x)\,rac{\partial u\,(x)}{\partial x_{i}}\,rac{\partial \overline{v\,(x)}}{\partial x_{k}}\,dx + \ &+ \int\limits_{\widetilde{S}} a\,(t\,,x)\,u\,(x)\overline{v\,(x)}\,d\sigma \ &\|u\|_{l}^{+} = ig((u\,,\,u))_{l}^{+}ig)^{1/2}. \end{aligned}$$

Let $\Lambda_0(t)$ be as it was in Lemma 5° of [6]. And again it is easy to see that the conditions:

$$\begin{cases} u \in D(\Lambda_0(t)), \\ ((\Lambda_0(t)u, v)) = ((u, v))_t^+, \ u \in D(\Lambda_0(t)), \ v \in H^1(\Omega) \end{cases}$$

imply the following ones:

(iv)
$$\begin{bmatrix} \sum_{i,k=1}^{n} \frac{\partial}{\partial x_{k}} \left(a_{ik}(t,x) \frac{\partial u}{\partial x_{i}} \right) \end{bmatrix} \epsilon L^{2}(\Omega) \\ A_{0}(t)u = u - \sum_{i,k=1}^{n} \frac{\partial}{\partial x_{k}} \left(a_{ik}(t,x) \frac{\partial u}{\partial x_{i}} \right) \end{bmatrix}$$

in the sense of $D'(\Omega)$. Let $u, v \in D(\overline{\Omega})$. We have

$$(\mathbf{v}) \qquad \int_{\Omega} -\sum_{i,k=1}^{n} \frac{\partial}{\partial x_{k}} \left(a_{ik}(t,x) \frac{\partial u}{\partial x_{i}} \right) \overline{v} dx = \int_{\Omega} \sum_{i,k=1}^{n} a_{ik}(t,x) \frac{\partial u}{\partial x_{i}} \frac{\partial \overline{v}}{\partial x_{k}} dx + \\ -\int_{S} \left(a_{ik}(t,x) \frac{\partial u}{\partial x_{i}} \eta_{k} \right) \overline{v} d\sigma .$$

Thus for every $u, v \in D(\overline{\Omega})$ from the equality $((\Lambda_0(t)u, v)) = ((u, v))_t^+$ it follows that

(vi)
$$\int\limits_{S} \left[a(t, x) u + \sum_{i,k=1}^{n} a_{ik}(t, x) \frac{\partial u}{\partial x_{i}} \eta_{k} \right] \overline{v} d\sigma = 0$$

Hence, for every $u \in D(\Omega) \cap D(\Lambda_0(t))$ we have

(vii)
$$\left\{\sum_{i,k=1}^{n} a_{ik}(t,x) \frac{\partial u}{\partial x_i} \eta_k + a(t,x) u\right\}_{/S} = 0$$
 in the sense of $L^2(S)$

Putting

$$S(t)u = -\sum_{i,k=1}^{n} a_{ik}(t,x) \frac{\partial^2 u}{\partial x_i \partial x_k} + \sum_{i,k=1}^{n} \frac{\partial}{\partial x_k} \left(o_{ik}(t,x) \frac{\partial u}{\partial x_i} \right) - u$$
$$B(t)u = \sum_{i=1}^{n} a_i(t,x) \frac{\partial u}{\partial x_i}$$

the equation (i) takes the form

(viii)
$$\frac{d^2u}{dt^2} + (\Lambda_0(t) + S(t))u + B(t)\frac{du}{dt} = 0.$$

Now we have to prove the conditions (2.1) - (2.3) of Theorem 2 of [6] are fulfilled.

The conditions (2.1) and (2.2) one verifies similarly as in Section II. Ad (2.3). For any $u \in D(\overline{\Omega})$ we have

$$ig(B(t)u,u)ig) = \int\limits_{\Omega} \sum\limits_{i=1}^n a_i(t,x) rac{\partial u}{\partial x_i} \, ar{u} dx - \int\limits_{\Omega} \sum\limits_{i=1}^n rac{\partial}{\partial x_i} ig(a_i(t,x)ar{u}) \, u dx + \int\limits_{S} \sum\limits_{i=1}^n a_i(t,x) |u|^2 \eta_i d\sigma = -ig((u,Bu)ig) - \int\limits_{\Omega} \sum\limits_{i=1}^n rac{\partial a_i(t,x)}{\partial x_i} |u|^2 dx$$

Thus, for any $u \in D(\overline{\Omega})$ the inequality $|\operatorname{Re}((B(t)u, u))| \leq c_1 ||u||^2$ holds. By the density of $D(\overline{\Omega})$ in $H^1(\Omega)$ and by the inequality $||u|| \leq ||u||_0^+$ for $u \in H^1(\Omega)$, condition (2.3) is proved.

Theorem 2 assures the existence and the uniqueness of the solution u(t, x) of problem (i) -(iii) such that $(u(t), u'(t)) \in D(A_2(t)) = D(\Lambda_0(t)) \times \times H^1(\Omega)$. Moreover, with the aid theorems of regularity we are able to prove that u(t) (more precisely $u(t, \cdot)$) belongs to $H^2(\Omega)$. Really, let us put

$$egin{aligned} & H^2(arOmega) = \left\{ u\,\epsilon\, H^2(arOmega): \left[\sum_{i,k=1}^n a_{ik}(t,\,x)\,rac{\partial u}{\partial x_i}\eta_k + a(t,\,x)\,u
ight]_{lS} = 0
ight\} \ & Dig(ilde{A}_2(t)) = H^2_t(arOmega) imes H^1(arOmega), \end{aligned}$$

(ix)

$$\tilde{A}_{2}(t) \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} 0 & , & 1 \\ -\Lambda(t) - S(t) & B(t) \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}, \text{ for } \begin{pmatrix} u \\ v \end{pmatrix} \in D\left(\tilde{A}_{2}(t)\right).$$

The following lemma ([3], p. 345, Lemma 2.3) holds

Lemma. There exists a constant $\lambda_1 > 0$ such that for any $\lambda > \lambda_1$ the operator $(\lambda - \tilde{A}_2(t))$ is a bijective mapping from $H^2_t(\Omega) \times H^1(\Omega)$ onto $H^1(\Omega) \times L^2(\Omega)$ and the following estimate holds

$$\| (\lambda - ilde{d}_2(t))^{-1} \|_{H^1(\Omega) imes L^2(\Omega)} \leqslant rac{1}{\lambda - \lambda_1},$$

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It has been proved in Lemma 2 of [6] that there exists a constant λ_0 such that for any $|\lambda| > \lambda_0$, $(\lambda - A_2(t))$ is a bijective mapping from $D(A_2(t))$ onto $H^+ \times H$. $(= H^1(\Omega) \times L^2(\Omega)$ in the present case). By (ix), $A_2(t)$ is an extension of $\tilde{A}_2(t)$, whereas by Lemma 2 it follows that $A_2(t) = \tilde{A}_2(t)$, hence $D(A_2(t)) = H_t^2(\Omega) \times H^1(\Omega)$.

The obtained result permits us to take the equality (iii) in the sense of the norm in $H^{1/2}(S)$ (for the spaces $H^k(S)$ and the tracetheorems cf. for instance [1] and [5].)

By (6°) of Theorem 2 it follows

$$u(t, \cdot) \in C^1(\langle 0, T \rangle; H^1(\Omega)) \cap C^2(\langle 0, T \rangle; L^2(\Omega)).$$

Furthermore,

$$(u'(t), u''(t)) = A_2(t)(u(t), u'(t)) \epsilon C^0(\langle 0, T \rangle; H_0^+ \times L^2(\Omega)),$$

hence, by known estimates (cf. [3], p. 343)

$$\|u\|_{H^2(\Omega)}^2 \leqslant c_1 \left(\left\| \sum_{i,j=1}^n a_{ij}(t,x) \frac{\partial^2 u}{\partial x_i \partial x_j} \right\|^2 + \|u\|^2 + \left\| \sum_{i,j=1}^n a_{ij}(t,x) \frac{\partial u}{\partial x_j} \eta_i \right\|_{H^{1/2}(S)}^2 \right)$$

we see that $u(t, \cdot) \in C^0(\langle 0, T \rangle; H^2(\Omega))$. And, in this way, we have proved the following

Theorem B. Given $\{u_0(x), u_1(x)\} \in H^2(\Omega) \times H^1(\Omega)$, if the conditions a) and b) are satisfied then there exists one and only one solution u(t, x)of the problem (i)-(iii) such that

$$u(t, \cdot) \in C^0(\langle 0, T \rangle; H^2(\Omega)) \cap C^1(\langle 0, T \rangle; H^1(\Omega)) \cap C^2(\langle 0, T \rangle; L^2(\Omega)).$$

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STRESZCZENIE

W pracy tej podaje się niektóre zastosowania twierdzeń uzyskanych w I do zadań mieszanych dla równań cząstkowych typu hiperbolicznego. Uzyskuje się twierdzenia dotyczące istnienia i jednoznaczności rozwiązania zadań brzegowych typu Dirichleta i typu transwersalnego.

РЕЗЮМЕ

В настоящей работе приводятся некоторыс применения теорем, полученных в I части к смешанным задачам для гиперболических уравнений с частными производными. Здесь получаются теоремы, касающиеся проблемы существования и единственности решения граничных задач типа Дирихле и трансверсального типа.